

Implementing Ohmmeter/Temperature Sensor

INTRODUCTION

This application note describes a method for implementing an ohmmeter or resistance type temperature sensor using the PIC16C5X series of microcontrollers. The ohmmeter requires only two external components and is software and hardware configurable for resistance measurement with resolutions from 6 bits up to 10 bits with measurement times of 250 μ s (6 bits at 8 MHz) or longer. The method uses a software calibration technique that compensates for voltage, time, and temperature drift as well as component errors. The PIC16C5X microcontrollers are ideal for simple analog applications because:

- * Very low cost.
- * Few external components required.
- * Fully programmable. PIC16C5X Microcontrollers are offered as One Time Programmable (OTP) EPROM devices.
- * Available off the shelf from distributors.
- * Calibration in software for improved measurement accuracy.
- * Power savings using PIC16C5X's Sleep mode.
- * PIC16C5X's output pins have large, current source/sink capability to drive LED's directly.

THEORY OF OPERATION

The application uses a capacitive charging circuit (Figure 1) to convert the resistance to time, which can be easily measured using a microcontroller. First, a reference voltage (usually V_{DD}) is applied to a calibration resistor, R_c . The capacitor C is charged up until the threshold on the chip input trips. This generates a software calibration value that is used to calibrate out most circuit errors, including inaccuracies in the capacitor, changes in the input threshold voltage and temperature variations. After C is discharged, the reference voltage is applied to the resistance to be measured (or thermistor). The time to trip the threshold is then measured and compared to the calibration value to determine the actual resistance (Figure 2). In the temperature sensing mode, the temperature is calculated using a lookup table.

FIGURE 1 - OHMMETER/TEMPERATURE SENSOR

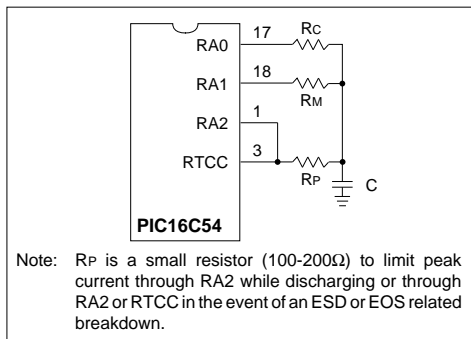
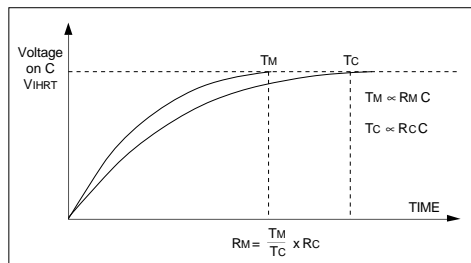


FIGURE 2 - OHMMETER/TEMPERATURE SENSOR



CIRCUIT CONFIGURATION

The values of R_c and C are selected based upon the number of bits of resolution required. R_c should be approximately one half the largest value resistance to be measured and:

$$C = \frac{-T}{R_M * \ln \left(1 - \frac{V_t}{V_r} \right)}$$

Where:

- V_r = Reference voltage
- T = Time to do the number of bits of resolution desired
- V_t = Threshold voltage of the PIC16C5X input being used
- R_M = Maximum resistance value to be measured

Actual value for C should be slightly smaller than calculated to ensure that the PIC16C5X does not overcount during the measurement.

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For example use $R_M=200K$ for 8-bits resolution with an 8 MHz clock, $V_r = 5V$, $V_t = 3V$, $R_c = 100K$ and 6 instruction cycles per count:

$$T = 256 \text{ counts} * 1/8 \text{ MHz} * 4 \text{ clocks/instruction} * 6 \text{ instructions/count} = 768 \mu\text{s}$$

$$C = 4200 \text{ pF [Use } 3900 \text{ pF]}$$

CIRCUIT PERFORMANCE

The calibration cycle removes all first order errors (offset, gain, C inaccuracy, power supply voltage and temperature) except R absolute accuracy. A low drift resistor should be selected for R and its value stored in software to reduce measurement errors. Other error sources are I/O pin leakage, resistor and capacitor non-linearities,

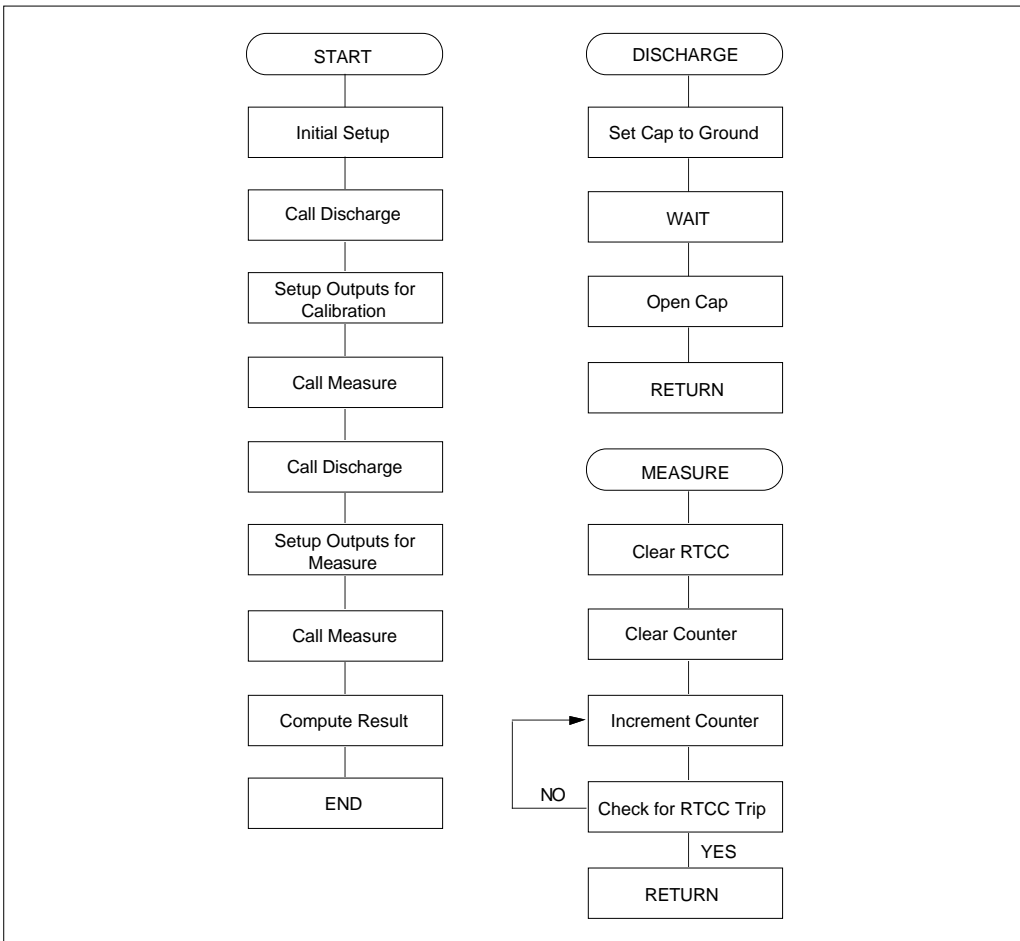
input threshold uncertainty and time measurement uncertainty (+/- one instruction cycle time). Measured performance shows the ohmmeter to be accurate within +/- 1% over one decade.

Example

The assembly code implementing the circuit of Figure 1 is listed in Appendix A. This code measures time up to 16 bits (65535 measure cycles) and calculates the results using 16 bit multiply and divide subroutines. In actual applications, it is more efficient to use 8 bit measurements if application accuracies permit. The math code will be substantially reduced and measurement time is reduced by the simpler code and shorter count.

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FIGURE 3 - TRANSMISSION FLOW CHART



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APPENDIX A:

MPASM B0.54

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```
LIST P=16C54,F=inhx8M

0008          ACCA EQU 8
000A          ACCB EQU 0A
000C          ACCC EQU 0C
000E          ACCD EQU 0E
0010          ACCE EQU 10
0012          TCAL EQU 12
0014          TEMP EQU 14

002F          RCALMS EQU 2F          ;RCAL MSB VALUE IN HEX
003C          RCALLS EQU 3C          ;RCAL LSB VALUE IN HEX

          ORG 1FF
01FF 0A58     GOTO OHMS
          ORG 0

0000 0209     MADD MOVF ACCA+1,W
0001 01EB     ADDWF ACCB+1          ;ADD LSB
0002 0603     BTFSC 3,0           ;ADD IN CARRY
0003 02AA     INCF ACCB
0004 0208     MOVF ACCA,W
0005 01EA     ADDWF ACCB          ;ADD MSB
0006 0800     RETLW 0
0007 0000     NOP

0008 0915     MPY CALL SETUP          ;RESULTS IN B(16 MSB'S) AND C(16 LSB'S)
0009 032E     MLOOP RRF ACCD          ;ROTATE D RIGHT
000A 032F     RRF ACCD+1
000B 0603     SKPNC
          ;NEED TO ADD?
000C 0900     CALL MADD
000D 032A     RRF ACCB
000E 032B     RRF ACCB+1
000F 032C     RRF ACCC
0010 032D     RRF ACCC+1
0011 02F4     DECFSZ TEMP          ;LOOP UNTIL ALL BITS CHECKED
0012 0A09     GOTO MLOOP
0013 0800     RETLW 0

0014 0000     NOP
0015 0C10     SETUP MOVLW 10
0016 0034     MOVWF TEMP
0017 020A     MOVF ACCB,W          ;MOVE B TO D
0018 002E     MOVWF ACCD
0019 020B     MOVF ACCB+1,W
001A 002F     MOVWF ACCD+1
001B 020C     MOVF ACCC,W
001C 0030     MOVWF ACCE
001D 020D     MOVF ACCC+1,W
001E 0031     MOVWF ACCE+1
001F 006A     CLRF ACCB
0020 006B     CLRF ACCB+1
0021 0800     RETLW 0
0022 0000     NOP
0023 0915     DIV CALL SETUP
0024 0C20     MOVLW 20
0025 0034     MOVWF TEMP
0026 006C     CLRF ACCC
0027 006D     CLRF ACCC+1
0028 0403     DLOOP CLRC
0029 0371     RLF ACCE+1
002A 0370     RLF ACCE
002B 036F     RLF ACCD+1
```

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```
002C 036E          RLF      ACCD
002D 036D          RLF      ACCC+1
002E 036C          RLF      ACCC
002F 0208          MOVF     ACCA,W
0030 008C          SUBWF   ACCC,W          ;CHECK IF A>C
0031 0743          SKPZ
0032 0A35          GOTO    NOCHK
0033 0209          MOVF     ACCA+1,W
0034 008D          SUBWF   ACCC+1,W      ;IF MSB EQUAL THEN CHECK LSB
0035 0703          NOCHK   SKPC          ;CARRY SET IF C>A
0036 0A3E          GOTO    NOGO
0037 0209          MOVF     ACCA+1,W      ;C-A INTO C
0038 00AD          SUBWF   ACCC+1
0039 0703          BTFSS   3,0
003A 00EC          DECF    ACCC
003B 0208          MOVF     ACCA,W
003C 00AC          SUBWF   ACCC
003D 0503          SETC
                                ;SHIFT A 1 INTO B (RESULT)
003E 036B          NOGO    RLF      ACCB+1
003F 036A          RLF      ACCB
0040 02F4          DECF    TEMP          ;LOOP UNTILL ALL BITS CHECKED
0041 0A28          GOTO    DLOOP
0042 0800          RETLW   0

0043 0C0B          DSCHRG  MOVLW  B'00001011'  ;ACTIVATE RA2
0044 0005          TRIS    5
0045 0CFF          MOVLW   0FF
0046 0034          MOVWF   TEMP
0047 02F4          LOOP    DECF    TEMP          ;WAIT
0048 0A47          GOTO    LOOP
0049 0C0F          MOVLW   B'00001111'  ;ALL OUTPUTS OFF
004A 0005          TRIS    5
004B 0800          RETLW   0

004C 0061          M_TIME  CLRF    1          ;CLEAR RTCC
004D 0069          CLRF    ACCA+1
004E 0068          CLRF    ACCA
004F 03E9          TLOOP   INCF    ACCA+1
0050 0A54          GOTO    ENDCHK
0051 03E8          INCF    ACCA
0052 0A54          GOTO    ENDCHK
0053 0A56          GOTO    END_M
0054 0701          ENDCHK  BTFSS   1,0      ;CHECK FOR RTCC TRIP
0055 0A4F          GOTO    TLOOP
0056 0201          END_M   MOVF     1,W
0057 0800          RETLW   0

0058 0C03          OHMS    MOVLW  B'00000011'  ;SET RA0 AND RA1 HIGH (ON WHEN ACTIVATED)
0059 0025          MOVWF   5
005A 0C28          MOVLW   B'00101000'  ;SELECT POSITIVE EDGE FOR RTCC
005B 0002          OPTION

005C 0943          CAL     CALL    DSCHRG          ;DISCHARGE CAPACITOR
005D 0C0E          MOVLW  B'00001110'  ;ACTIVATE RA0
005E 0005          TRIS    5
005F 094C          CALL    M_TIME          ;MEASURE TIME
0060 0209          MOVF     ACCA+1,W
0061 0033          MOVWF   TCAL+1        ;STORE LSB
0062 0208          MOVF     ACCA,W
0063 0032          MOVWF   TCAL          ;STORE MSB

0064 0943          MEAS    CALL    DSCHRG          ;DISCHARGE CAPACITOR
0065 0C0D          MOVLW  B'00001101'  ;ACTIVATE RA1
0066 0005          TRIS    5
0067 094C          CALL    M_TIME          ;MEASURE TIME

0068 0C3C          MOVLW  RCALLS          ;CALIBRATION LSB VALUE
0069 002B          MOVWF   ACCB+1
006A 0C2F          MOVLW  RCALMS          ;CALIBRATION MSB VALUE
```

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```
006B 002A          MOVWF  ACCB
006C 0908          CALL  MPY           ;MULTIPLY ACCA(MEAS) * ACCB(RCAL)
006D 0213          MOVF  TCAL+1,W
006E 0029          MOVWF ACCA+1
006F 0212          MOVF  TCAL,W
0070 0028          MOVWF  ACCA
0071 0923          CALL  DIV           ;DIVIDE ACCB(MEAS * R) BY ACCA(TCAL)
0072 0A58          GOTO  OHMS
                  END
```

```
Errors   :    0
Warnings :    0
```

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