



Saving and Restoring Status on Interrupt (Implementing a Parameter Stack)

INTRODUCTION

The PIC17C42 has a 16 level deep hardware stack. The program counter is pushed into this stack on interrupts and subroutine calls. However, other key registers are not saved in the stack. Registers such as W, ALUSTA (which has carry, zero and other flag bits) and the bank select register (BSR) must be saved in an interrupt service routine. The following macros, PUSH and POP implement a parameter stack in data memory to accomplish this.

The indirect addressing register FSR0 is used to implement this parameter stack. It is assumed that FSR0 and its control bits are not used or modified elsewhere. The stack pointer (FSR0) is initialized at the highest RAM location (FFh).

```

Main_prog      SETF      FSR0              ;Initialize and dedicate FSR0 as stack pointer
               BCF      ALUSTA,FS0      ;
               BCF      ALUSTA,FS1      ;Set-up FSR0 for auto-dec
               .
               .
               .
PUSH           MACRO
               BCF      ALUSTA,FS0      ;Set-up FSR0 for auto-dec
               MOVFP   ALUSTA,IND0      ;Save ALUSTA first
               MOVFP   BSR,IND0        ;
               MOVFP   W,IND0          ;
               MOVFP   RAM_x, IND0      ;Now save general
               MOVFP   RAM_y, IND0      ;Purpose registers
               ENDM
POP            MACRO
               BSF      ALUSTA,FS0      ;Set-up for auto-inc
               INCF    FSR0             ;
               MOVFP   IND0, RAM_y      ;
               MOVFP   IND0, RAM_x      ;
               MOVFP   IND0,W          ;
               MOVFP   IND0,BSR        ;
               MOVFP   IND0,ALUSTA      ;restore ALUSTA last
               DECF    FSR0             ;Adjust stack pointer
               ENDM
               .
               .
               .
interrupt_routine
               PUSH     ;save registers
               .
               .
               .
;main body of interrupt service
               .
               .
               .
               POP      ;restore status
               RETFIE   ;return

```

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While the macros are quite self-explanatory, the user should note a few subtle points.

1. `MOVFP` instruction does not affect status flags while `MOVFF` does.
2. `MOVFP` and `MOVFF` are used such that any register can be saved and restored. Note that register being saved or restored has address `f` (which can be 00h to FFh) and other address, `IND0` (indirect), therefore, can be any address.
3. `FSR` auto-increments or auto-decrements after the operation ('post'). Therefore, in the `POP` macro pre-increment is simulated.
4. All interrupts should be disabled when executing the `PUSH` and `POP` instructions. While `PUSH` will have the `GIE` bit disabled, `POP` may not necessarily have the `GIE` bit disabled. The user should disable the `GIE` bit when executing the `POP`.

Using this scheme, interrupts and subroutine calls can be nested, since the stack will grow and shrink. The stack can be used to pass parameters to subroutines.

*Author: Stan D'Souza
Logic Products Division*

WORLDWIDE SALES & SERVICE

AMERICAS

Corporate Office

Microchip Technology Inc.
2355 West Chandler Blvd.
Chandler, AZ 85224-6199
Tel: 602 786-7200 Fax: 602 786-7277
Technical Support: 602 786-7627
Web: <http://www.mchip.com/microhip>

Atlanta

Microchip Technology Inc.
500 Sugar Mill Road, Suite 200B
Atlanta, GA 30350
Tel: 770 640-0034 Fax: 770 640-0307

Boston

Microchip Technology Inc.
5 Mount Royal Avenue
Marlborough, MA 01752
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Microchip Technology Inc.
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Itasca, IL 60143
Tel: 708 285-0071 Fax: 708 285-0075

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14651 Dallas Parkway, Suite 816
Dallas, TX 75240-8809
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35 Rockridge Road
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Tel: 513 832-2543 Fax: 513 832-2841

Los Angeles

Microchip Technology Inc.
18201 Von Karman, Suite 455
Irvine, CA 92715
Tel: 714 263-1888 Fax: 714 263-1338

New York

Microchip Technology Inc.
150 Motor Parkway, Suite 416
Hauppauge, NY 11788
Tel: 516 273-5305 Fax: 516 273-5335

AMERICAS (continued)

San Jose

Microchip Technology Inc.
2107 North First Street, Suite 590
San Jose, CA 95131
Tel: 408 436-7950 Fax: 408 436-7955

ASIA/PACIFIC

Hong Kong

Microchip Technology
Unit No. 3002-3004, Tower 1
Metroplaza
223 Hing Fong Road
Kwai Fong, N.T. Hong Kong
Tel: 852 2 401 1200 Fax: 852 2 401 3431

Korea

Microchip Technology
168-1, Youngbo Bldg. 3 Floor
Samsung-Dong, Kangnam-Ku,
Seoul, Korea
Tel: 82 2 554 7200 Fax: 82 2 558 5934

Singapore

Microchip Technology
200 Middle Road
#10-03 Prime Centre
Singapore 188980
Tel: 65 334 8870 Fax: 65 334 8850

Taiwan

Microchip Technology
10F-1C 207
Tung Hua North Road
Taipei, Taiwan, ROC
Tel: 886 2 717 7175 Fax: 886 2 545 0139

EUROPE

United Kingdom

Arizona Microchip Technology Ltd.
Unit 6, The Courtyard
Meadow Bank, Furlong Road
Bourne End, Buckinghamshire SL8 5AJ
Tel: 44 0 1628 851077 Fax: 44 0 1628 850259

France

Arizona Microchip Technology SARL
2 Rue du Buisson aux Fraises
91300 Massy - France
Tel: 33 1 69 53 63 20 Fax: 33 1 69 30 90 79

Germany

Arizona Microchip Technology GmbH
Gustav-Heinemann-Ring 125
D-81739 Muenchen, Germany
Tel: 49 89 627 144 0 Fax: 49 89 627 144 44

Italy

Arizona Microchip Technology SRL
Centro Direzionale Colleoni
Palazzo Pegaso Ingresso No. 2
Via Paracelso 23, 20041
Agrate Brianza (MI) Italy
Tel: 39 039 689 9939 Fax: 39 039 689 9883

JAPAN

Microchip Technology Intl. Inc.
Benex S-1 6F
3-18-20, Shin Yokohama
Kohoku-Ku, Yokohama
Kanagawa 222 Japan
Tel: 81 45 471 6166 Fax: 81 45 471 6122

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