

Adaptive Differential Pulse Code Modulation using PIC16/17 Microcontrollers

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INTRODUCTION

In the past, adding speech recording and playback capability to a product meant using a digital signal processor or a specialized audio chip. Now, using a simplified Adaptive Differential Pulse Code Modulation (ADPCM) algorithm, these audio capabilities can be added to any PIC16/17 device. This application note will cover the ADPCM compression and decompression algorithms, performance comparison of all PIC16/17 devices, and an application using a PIC16C72 microcontroller.

DEFINITION OF TERMS

step size - value of the step used for quantization of analog signals and inverse quantization of a number of steps.
quantization - the digital form of an analog input signal is represented by a finite number of steps.

adaptive quantization - the step size of a quantizer is dramatically changed with time in order to adapt to a changing input signal.

inverse quantizer - a finite number of steps is converted into a digital representation of an analog signal.

THEORY OF OPERATION

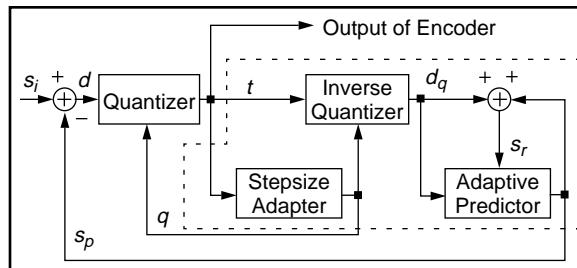
The ADPCM algorithm takes advantage of the high correlation between consecutive speech samples, which enables future sample values to be predicted. Instead of encoding the speech sample, ADPCM encodes the difference between a predicted sample and the speech sample. This method provides more efficient compression with a reduction in the number of bits per sample, yet preserves the overall quality of the speech signal. The implementation of the ADPCM algorithm provided in this application note is based on the Interactive Multimedia Association's (IMA) Recommended Practices for Enhancing Digital Audio Compatibility in Multimedia Systems revision 3.00. The ITU (formerly CCITT) G.721 ADPCM algorithm is well known and has been implemented on many digital signal processors such as the TMS320 family from Texas Instruments and the ADSP-2100 family from

Analog Devices. ITU G.721 uses floating point arithmetic and logarithmic functions which are not easily implemented in the 8-bit microcontroller world. The IMA Reference algorithm significantly reduces the mathematical complexity of ITU G.721 by simplifying many of the operations and using table lookups where appropriate.

COMPRESSION

The input, s_i , to the encoder routine must be 16-bit two's complement speech data. The range of allowable values for s_i is 32767 to -32768. Figure 1 shows a block diagram for ADPCM compression and Appendix A has a listing of the function **ADPCMEncoder()**. The predicted sample, s_p , and the quantizer step size index are saved in a structure for the next iteration of the encoder. Initially, the quantizer step size index and the predicted sample (s_p) are set to zero. The encoder function takes a 16-bit two's complement speech sample and returns an 8-bit number containing the 4-bit sign-magnitude ADPCM code.

FIGURE 1: ADPCM ENCODER BLOCK DIAGRAM



The predicted sample, s_p , is subtracted from the linear input sample, s_i , to produce a difference, d . Adaptive quantization is performed on the difference, resulting in the 4-bit ADPCM value, t . The encoder and decoder both update their internal variables based on this ADPCM value. A full decoder is actually embedded within the encoder. This ensures that the encoder and decoder are synchronized without the need to send any additional data. The embedded decoder is shown within the dotted lines of Figure 1. The embedded decoder uses the ADPCM value to update the inverse quantizer, which produces a dequantized version, d_q , of the difference, d . The implementation of the ADPCM algorithm presented in this application note uses a

fixed predictor instead of an adaptive predictor which reduces the amount of data memory and instruction cycles required.

The adaptive predictor of ITU G.721 adjusts according to the value of each input sample using a weighted average of the last six dequantized difference values and the last two predicted values. So at this point, the

dequantized difference, d_q , is added to the predicted sample, s_p , to produce a new predicted sample, s_r . Finally the new predicted sample, s_r , is saved into s_p .

The following (Table 1) is a step-by-step description of the **ADPCMEncoder()** function from Appendix A.

TABLE 1: ADPCMEncoder() STEP-BY-STEP FUNCTIONS

1. ADPCMEncoder takes a 16-bit signed number (speech sample, 32767 to -32768) and returns an 8-bit number containing the 4-bit ADPCM code (0-15)
2. Restore the previous values of predicted sample (s_p) and the quantizer step size index
3. Find the quantizer step size (q) from a table lookup using the quantizer step size index
4. Compute the difference (d) between the actual sample (s_i) and the predicted sample (s_p)
5. Set the sign bit of the ADPCM code (t) if necessary and find the absolute value of difference ($|d|$)
6. Save quantizer step size (q) in a temporary variable
7. Quantize the difference (d) into the ADPCM code (t) using the quantizer step size (q)
8. Inverse quantize the ADPCM code (t) into a predicted difference (d_q) using the quantizer step size (q)

```
char ADPCMEncoder(long signed sample)

predsample = state.prevsample;
index = state.previndex;

step = StepSizeTable[index];

diff = sample - predsample;

if(diff >= 0)
    code = 0;
else
{
    code = 8;
    diff = - diff;
}

tempstep = step;

if(diff >= tempstep)
{
    code |= 4;
    diff -= tempstep;
}
tempstep >>= 1;
if(diff >= tempstep)
{
    code |= 2;
    diff -= tempstep;
}
tempstep >>= 1;
if(diff >= tempstep)
    code |= 1;

diffq = step >> 3;
if(code & 4)
    diffq += step;
if(code & 2)
    diffq += step >> 1;
if(code & 1)
    diffq += step >> 2;
```

TABLE 1: ADPCMEncoder() STEP-BY-STEP FUNCTIONS (CONTINUED)

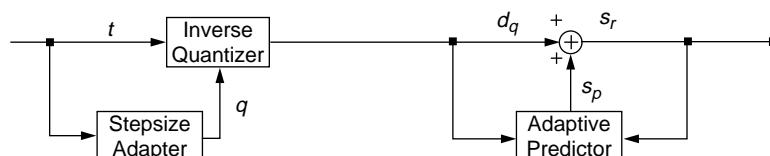
9. Fixed predictor computes new predicted sample (s_p) by adding the old predicted sample (s_p) to the predicted difference (d_q)	<pre>if(code & 8) predsample -= diffq; else predsample += diffq;</pre>
10. Check for overflow of the new predicted sample (s_p). s_p , which is a signed 16-bit sample, must be in the range of 32767 to -32768	<pre>if(predsample > 32767) predsample = 32767; else if(predsample < -32768) predsample = -32768;</pre>
11. Find the new quantizer step size index (q) by adding the previous index and a table lookup using the ADPCM code (t)	<pre>index += IndexTable[code];</pre>
12. Check for overflow of the new quantizer step size index	<pre>if(index < 0) index = 0; if(index > 88) index = 88;</pre>
13. Save the new predicted sample (s_p) and quantizer step size index for next iteration	<pre>state.prevsample = predsample; state.previndex = index;</pre>
14. Return the ADPCM code (t)	<pre>return (code & 0x0f);</pre>

This function requires five 16-bit variables and two 8-bit variables. Some optimizations can be made to the code in Appendix A such as combining steps 7 and 8. Appendix C gives the output listing of the MPC compiler for a PIC16CXX device using the optimized encoder algorithm and the decoder algorithm from the next section.

DECOMPRESSION

The input into the decoder, t , must be an 8-bit number containing the 4-bit ADPCM data in sign-magnitude format. The range of allowable values for t is 0 to 15, where 7 = 0x07 and -7 = 0x0F. Figure 2 shows a block diagram for ADPCM decompression and Appendix B has a listing of the function **ADPCMDecoder()**. The predicted sample, s_p , and the quantizer step size index are saved in a structure for the next iteration of the decoder. Initially, the quantizer step size index and the

predicted sample (s_p) are set to zero. This function takes a 4-bit sign-magnitude ADPCM code and returns the 16-bit two's complement speech sample. This decoder is the same as the one used in the encoder routine. It uses the ADPCM value to update the inverse quantizer, which produces a difference, d_q . The difference, d_q , is added to the predicted sample, s_p , to produce the output sample, s_r . The output sample, s_r , is then saved into the predicted sample, s_p , for the next iteration of the decoder.

FIGURE 2: ADPCM DECODER BLOCK DIAGRAM

The following (Table 2) is a step-by-step description of the **ADPCMDecoder()** function from Appendix B.

TABLE 2: ADPCMDecoder() STEP-BY-STEP FUNCTIONS

1. ADPCMDecoder takes an 8-bit number containing the 4-bit ADPCM code (0-15) and returns a 16-bit signed number (speech sample, 32767 to -32768)
2. Restore the previous values of predicted sample (s_p) and quantizer step size index
3. Find the quantizer step size (q) from a table lookup using the quantizer step size index
4. Inverse quantize the ADPCM code (t) into a predicted difference (d_q) using the quantizer step size (q)
5. Fixed predictor computes new predicted sample (s_r) by adding the old predicted sample (s_p) to the predicted difference (d_q)
6. Check for overflow of the new predicted sample (s_r). s_r , which is a signed 16-bit sample, must be in the range of 32767 to -32768
7. Find the new quantizer step size (q) by adding the previous index and a table lookup using the ADPCM code (t)
8. Check for overflow of the new quantizer step size index
9. Save the new predicted sample (s_r) and quantizer step size index for next iteration
10. Return the new sample (s_r)

```
signed long ADPCMDecoder( char code )  
  
    predsample = state.prevsample;  
    index = state.previndex;  
  
    step = StepSizeTable[index];  
  
    diffq = step >> 3;  
    if(code & 4)  
        diffq += step;  
    if(code & 2)  
        diffq += step >> 1;  
    if(code & 1)  
        diffq += step >> 2;  
  
    if(code & 8)  
        predsample -= diffq;  
    else  
        predsample += diffq;  
  
    if(predsample > 32767)  
        predsample = 32767;  
    else if(predsample < -32768)  
        predsample = -32768;  
  
    index += IndexTable[code];  
  
    if(index < 0)  
        index = 0;  
    if(index > 88)  
        index = 88;  
  
    state.prevsample = predsample;  
    state.previndex = index;  
  
    return ( predsample );
```

This function requires three 16-bit variables and one 8-bit variable. Appendix C gives the listing output of the MP-C compiler of the decoder algorithm and the optimized encoder algorithm.

IMA ADPCM REFERENCE ALGORITHM

The IMA, specifically the Digital Audio Technical Working Group, is a trade association with representatives from companies such as Compaq®, Apple Computer®, Crystal Semiconductor®, DEC®, Hewlett-Packard®, Intel®, Microsoft®, Sony®, and Texas Instruments® to name a few. This group is working towards a standard that defines the exchange of high quality audio data between computing platforms. The algorithm from Intel/DVI® (Digital Video Interactive) has been selected as the standard due to its audio dynamic range and low data rate. The recommended digital audio exchange formats are given in Table 3.

The algorithms that are implemented in this application note were derived from the IMA ADPCM Reference algorithm. The data format is 8.0 kHz, mono, 4-bit ADPCM. Essentially, the compression and decompression use an adaptive quantization with fixed prediction. The adaptive quantization are based on a

table lookup first developed by Intel/DVI for the IMA. Appendix D gives the information about IMA and the supporting documentation for IMA ADPCM.

PERFORMANCE

Table 4 shows the performance comparison of the ADPCM compression and decompression routines for the PIC16C5X, PIC16CXX, and PIC17CXX family of devices assuming 80 additional instruction cycles for overhead. Any device without a PWM module will have to increase the operating frequency to generate a software PWM. Table 4 also provides the minimum external operating frequency required to run the routines. The C code from Appendix C was used. The input/output data rate of the speech samples is 8.0 kHz. The minimum operating frequency is calculated as follows:

$$8000 \times \# \text{ of Total Instruction Cycles} \times 4.$$

For example, the ADPCM encoding using the PIC16CXX family would require an $8000 \times (225 + 80) \times 4 = 9.760 \text{ MHz}$ external crystal.

TABLE 3: DIGITAL AUDIO EXCHANGE FORMATS

Sampling Rate	Mono/Stereo	Data Format	Notes
8.0 kHz	mono	8-bit μ-Law PCM	CCITT G.711 Standard
	mono	8-bit A-Law PCM	CCITT G.711 Standard
	mono	4-bit ADPCM	DVI Algorithm
11.025 kHz	mono/stereo	8-bit Linear PCM	Macintosh® & MP-C Standard
	mono/stereo	4-bit ADPCM	DVI Algorithm
22.05 kHz	mono/stereo	8-bit Linear PCM	Macintosh & MPC Standard
	mono/stereo	4-bit ADPCM	DVI Algorithm
44.10 kHz	mono/stereo	16-bit Linear PCM	CD-DA Standard
	mono/stereo	4-bit ADPCM	DVI Algorithm

TABLE 4: PERFORMANCE COMPARISON TABLE

Device	Encode/Decode	# of Instruction Cycles	Minimum External Operating Frequency
PIC16C5X	Encode	273	11.296 MHz
	Decode	208	9.216 MHz
PIC16CXX	Encode	225	9.760 MHz
	Decode	168	7.936 MHz
PIC17CXX	Encode	199	8.928 MHz
	Decode	161	7.712 MHz

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Table 5 illustrates the amount of program and data memory that the ADPCM algorithms consume for the various PIC16/17 devices. The program memory numbers may change slightly depending on the specific device being used. The table memory column shows how much program memory is used to store the two lookup tables used by the ADPCM algorithm.

TABLE 5: DEVICE MEMORY CONSUMED

Device		Program Memory (words)	Data Memory (bytes)	Table Lookup (words)
PIC16C5X	Encode	273	13	196
	Decode	205	10	
PIC16CXX	Encode	220	13	196
	Decode	162	10	
PIC17CXX	Encode	203	13	97
	Decode	164	10	

APPLICATION

The hardware for this application note implements only the decompression algorithm, but the compression algorithm is also included in the firmware. A block diagram is shown in Figure 3 and the schematic is provided in Appendix E. The complete source code listing, including a block diagram, is given in Appendix F. The board uses a PIC16C72, rated for 20 MHz operation, to control the speech decoding and output. The A/D (Analog-to-Digital) converter of the PIC16C72 is not used in this design. Two 27C512A EPROMs from Microchip Technology are used to store up to 32.768 seconds of ADPCM data. Each EPROM holds 65536 bytes. Each byte in the EPROM contains two ADPCM values. One second of speech requires 8000 ADPCM codes (8 kHz sample rate). Therefore, each EPROM holds $(65536 \times 2) / 8000 = 16.384$ seconds of speech. A 16-bit up counter is used to clock data out of the EPROMs. This method uses only two I/O lines to control the counter and eleven I/O lines to read the EPROM data.

Speech regeneration is accomplished by using the Capture/Compare/PWM (CCP) module of the PIC16C72. The PWM module is configured for a period of 32 kHz. This allows each sample of the speech signal to be output for four PWM periods. The period is

calculated by using the following equation from Section 10.3 of the PIC16C7X Data Sheet (DS30390). From the following calculation, PR2 is set to a value of 155.

$$\text{PWM period} = [\text{PR2} + 1] * 4 * \text{Tosc} * \\ (\text{TMR2 prescale value})$$

$$1 / 32 \text{ kHz} = [\text{PR2} + 1] * 4 * (1 / 20 \text{ MHz}) * 1$$

$$31.25 \mu\text{s} = [\text{PR2} + 1] * 4 * 50 \text{ ns} * 1$$

$$156.25 = \text{PR2} + 1$$

$$155.25 = \text{PR2}$$

The CCP module has the capability of up to 10-bit resolution for the PWM duty cycle. The maximum resolution of the duty cycle that can be achieved for a 32 kHz period can be calculated using the following equation from Section 10.3 of the PIC16C7X Data Sheet.

$$\text{PWM duty cycle} = \text{DC}<10:0> * \text{Tosc} * \\ (\text{TMR2 prescale value})$$

where $\text{DC}<10:0> = 2^x$ where x = bits of resolution

$$1 / 32 \text{ kHz} = 2^x * (1 / 20 \text{ MHz}) * 1$$

$$31.25 \mu\text{s} = 2^x * 50 \text{ ns} * 1$$

$$625 = 2^x$$

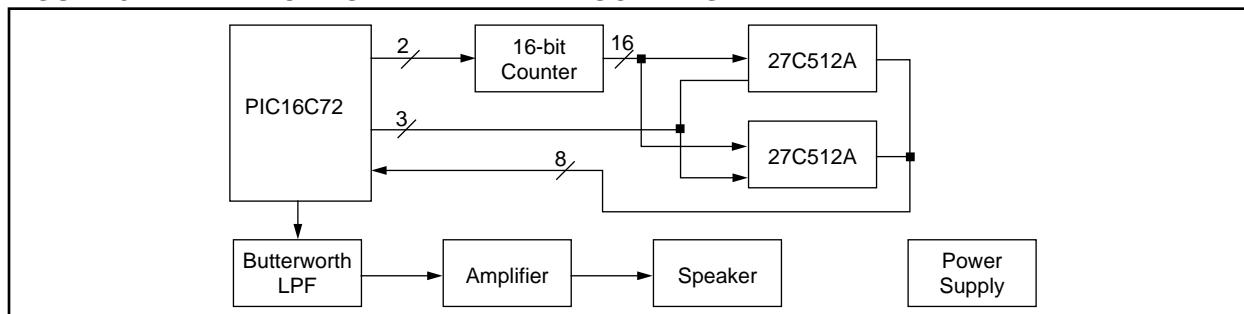
$$\log(625) = \log(2^x)$$

$$\log(625) = x * \log(2)$$

$$9.3 = x$$

A PWM duty cycle with up to 9-bits of resolution may be used with a period of 32 kHz. The upper 9-bits of each speech sample are used to set the PWM duty cycle ($\text{CCPR1L} = \text{sample}<15:9>$, $\text{CCP1CON}<5:4> = \text{sample}<8:7>$). This PWM speech signal is passed through a 4th-order Butterworth low pass filter with a corner frequency of 4 kHz. The low pass filter converts the PWM into an analog voltage level. Finally, the analog voltage level is amplified by a National Semiconductor LM386N-3 before entering the speaker. Every 125 μs (8 kHz) one ADPCM code must be converted into a speech sample for output to the PWM. This frame of 125 μs relates to 625 instruction cycles for an external crystal frequency of 20 MHz. The ADPCM decode routine, EPROM reads and writes to the PWM must be accomplished within 625 instruction cycles.

FIGURE 3: APPLICATION HARDWARE BLOCK DIAGRAM



To implement audio recording, the following changes to the application hardware would have to be made:

- Replace the EPROMs with RAM and
- Add a microphone with input filtering and
- Use the on-board A/D converter of the PIC16C7X devices for 8-bit recording or
- Use an external 12- to 16-bit A/D converter for better quality recording

The following is the sequence of events to record and store speech data. A timer would be used to set the sample rate. When the timer overflowed an A/D conversion would be started.

1. Start an A/D conversion when the timer overflows.
2. Read the sample and call the routine ADPCMEncoder().
3. Store the result in the upper 4-bits of a temporary variable.
4. Start an A/D conversion when the timer overflows.
5. Read the sample and call the routine ADPCMEncoder().
6. Store the result in the lower 4-bits of the temporary variable.
7. Write the temporary variable to the SRAM.
8. GOTO 1.

Typical conversion times for the PIC16C7X devices are 40 μ s. Assuming that the external crystal frequency is 20 MHz and the sample rate is 8 kHz, the encoder routine takes approximately 45 μ s (225 instruction cycles \times 700 μ s) to complete. This leaves approximately 40 μ s or 200 instruction cycles to read the A/D converter, write to the SRAM and complete any other tasks. An external A/D converter that is faster could be used to increase the amount of time for processing other tasks.

COMPUTER PROGRAM

The IMA Reference ADPCM algorithm was written for a PC using Borland C++ version 3.1. This program uses the same routines that are used in Appendix C. A raw sound file is recorded on the PC using a 16-bit sound card. Speech is recorded at 8.0 kHz in 16-bit mono mode. This raw speech file is processed by the encoder part of the program which creates a file with the ADPCM values. This file can now be burned into EPROMs for use with the application hardware. The decoder part of the program can take this file and create a new 16-bit raw speech file. The 16-bit sound card on the PC can play this file to ensure that the ADPCM compression/decompression routines are working properly. The PC program is given in Appendix F. It is composed of three files: pcspeech.c, pcadpcm.c, and pcadpcm.h.

CONCLUSION

The final results of the application hardware using the PIC16C72 are:

- Compression and Decompression
 - 906 words of Program Memory used
 - 44% of total Program Memory
 - 24 bytes of Data Memory used
 - 19% of total Data Memory
- Decompression only
 - 686 words of Program Memory used
 - 33% of total Program Memory
 - 22 bytes of Data Memory used
 - 17% of total Data Memory
- ~250 Instruction cycles to decode one ADPCM code
 - 40% of frame (250/625)
- Hardware used
 - CCP1 configured for PWM (9-bit duty cycle, 32 kHz period speech output)
 - Timer2 to set the 8.0 kHz output sample rate
 - 13 I/O lines to read data from the EPROMs

References:

1. *Recommended Practices for Enhancing Digital Audio Compatibility in Multimedia Systems*, Revision 3.00, Interactive Multimedia Association, October 21, 1992.
2. *Digital Audio Special Edition Proceedings*, Volume 2, Issue 2, Interactive Multimedia Association, May 1992.
3. Panos E. Papamichalis Ph.D., *Practical Approaches to Speech Coding*, Prentice-Hall Inc., Englewood Cliffs, N.J., 1987.
4. Adaptive Differential Pulse-Code Modulation, *Digital Signal Processing Applications using the ADSP-2100 Family*, Volume 1, Analog Devices, Prentice-Hall, Englewood Cliffs, N.J., 1992.
5. 32-kbits/s ADPCM with the TMS32010, *Digital Signal Processing Applications with the TMS320 Family*, SPRA012, Jay Reimer, Mike McMahan, and Masud Arjmand, Texas Instruments, 1986.

APPENDIX A: ADPCMEncoder() FUNCTION

```
/* Table of index changes */
const int IndexTable[16] = {
    0xff, 0xff, 0xff, 0xff, 2, 4, 6, 8,
    0xff, 0xff, 0xff, 0xff, 2, 4, 6, 8
};

/* Quantizer step size lookup table */
const long StepSizeTable[89] = {
    7, 8, 9, 10, 11, 12, 13, 14, 16, 17,
    19, 21, 23, 25, 28, 31, 34, 37, 41, 45,
    50, 55, 60, 66, 73, 80, 88, 97, 107, 118,
    130, 143, 157, 173, 190, 209, 230, 253, 279, 307,
    337, 371, 408, 449, 494, 544, 598, 658, 724, 796,
    876, 963, 1060, 1166, 1282, 1411, 1552, 1707, 1878, 2066,
    2272, 2499, 2749, 3024, 3327, 3660, 4026, 4428, 4871, 5358,
    5894, 6484, 7132, 7845, 8630, 9493, 10442, 11487, 12635, 13899,
    15289, 16818, 18500, 20350, 22385, 24623, 27086, 29794, 32767
};

signed long diff;           /* Difference between sample and predicted sample */
long step;                 /* Quantizer step size */
signed long predsample;    /* Output of ADPCM predictor */
signed long diffq;         /* Dequantized predicted difference */
int index;                 /* Index into step size table */

/*********************************************
*      ADPCMEncoder - ADPCM encoder routine
*****
*      Input Variables:
*          signed long sample - 16-bit signed speech sample
*      Return Variable:
*          char - 8-bit number containing the 4-bit ADPCM code
*****/
```

char ADPCMEncoder(signed long sample)

```
{
```

int code; /* ADPCM output value */
 int tempstep; /* Temporary step size */

/* Restore previous values of predicted sample and quantizer step
size index
*/
 predsample = state.prevsample;
 index = state.previndex;
 step = StepSizeTable[index];

/* Compute the difference between the actual sample (sample) and the
the predicted sample (predsample)
*/
 diff = sample - predsample;
 if(diff >= 0)
 code = 0;
 else
 {
 code = 8;
 diff = -diff;
 }

 /* Quantize the difference into the 4-bit ADPCM code using the
the quantizer step size
*/
 tempstep = step;
 if(diff >= tempstep)
 {
 code |= 4;

```
    diff -= tempstep;
}
tempstep >= 1;
if( diff >= tempstep )
{
    code |= 2;
    diff -= tempstep;
}
tempstep >= 1;
if( diff >= tempstep )
    code |= 1;

/* Inverse quantize the ADPCM code into a predicted difference
   using the quantizer step size
*/
diffq = step >> 3;
if( code & 4 )
    diffq += step;
if( code & 2 )
    diffq += step >> 1;
if( code & 1 )
    diffq += step >> 2;

/* Fixed predictor computes new predicted sample by adding the
   old predicted sample to predicted difference
*/
if( code & 8 )
    predsample -= diffq;
else
    predsample += diffq;

/* Check for overflow of the new predicted sample
*/
if( predsample > 32767 )
    predsample = 32767;
else if( predsample < -32768 )
    predsample = -32768;

/* Find new quantizer stepsize index by adding the old index
   to a table lookup using the ADPCM code
*/
index += IndexTable[code];

/* Check for overflow of the new quantizer step size index
*/
if( index < 0 )
    index = 0;
if( index > 88 )
    index = 88;

/* Save the predicted sample and quantizer step size index for
   next iteration
*/
state.prevsample = predsample;
state.previndex = index;

/* Return the new ADPCM code */
return ( code & 0x0f );
}
```

APPENDIX B: ADPCMDecoder() FUNCTION

```
/* Table of index changes */
const int IndexTable[16] = {
    0xff, 0xff, 0xff, 0xff, 2, 4, 6, 8,
    0xff, 0xff, 0xff, 0xff, 2, 4, 6, 8
};

/* Quantizer step size lookup table */
const long StepSizeTable[89] = {
    7, 8, 9, 10, 11, 12, 13, 14, 16, 17,
    19, 21, 23, 25, 28, 31, 34, 37, 41, 45,
    50, 55, 60, 66, 73, 80, 88, 97, 107, 118,
    130, 143, 157, 173, 190, 209, 230, 253, 279, 307,
    337, 371, 408, 449, 494, 544, 598, 658, 724, 796,
    876, 963, 1060, 1166, 1282, 1411, 1552, 1707, 1878, 2066,
    2272, 2499, 2749, 3024, 3327, 3660, 4026, 4428, 4871, 5358,
    5894, 6484, 7132, 7845, 8630, 9493, 10442, 11487, 12635, 13899,
    15289, 16818, 18500, 20350, 22385, 24623, 27086, 29794, 32767
};

long step;                      /* Quantizer step size */
signed long predsample;          /* Output of ADPCM predictor */
signed long diffq;              /* Dequantized predicted difference */
int index;                      /* Index into step size table */

/*********************************************
*      ADPCMDecoder - ADPCM decoder routine
*****
*      Input Variables:
*          char code - 8-bit number containing the 4-bit ADPCM code
*      Return Variable:
*          signed long - 16-bit signed speech sample
*****
*signed long ADPCMDecoder(char code )
{
    /* Restore previous values of predicted sample and quantizer step
       size index
    */
    predsample = state.prevsample;
    index = state.previndex;

    /* Find quantizer step size from lookup table using index
    */
    step = StepSizeTable[index];

    /* Inverse quantize the ADPCM code into a difference using the
       quantizer step size
    */
    diffq = step >> 3;
    if( code & 4 )
        diffq += step;
    if( code & 2 )
        diffq += step >> 1;
    if( code & 1 )
        diffq += step >> 2;

    /* Add the difference to the predicted sample
    */
    if( code & 8 )
        predsample -= diffq;
    else
        predsample += diffq;

    /* Check for overflow of the new predicted sample
    */
}
```

```
/*
if( predsample > 32767 )
    predsample = 32767;
else if( predsample < -32768 )
    predsample = -32768;

/* Find new quantizer step size by adding the old index and a
   table lookup using the ADPCM code
*/
index += IndexTable[code];

/* Check for overflow of the new quantizer step size index
*/
if( index < 0 )
    index = 0;
if( index > 88 )
    index = 88;

/* Save predicted sample and quantizer step size index for next
   iteration
*/
state.prevsample = predsample;
state.previndex = index;

/* Return the new speech sample */
return( predsample );

}
```

APPENDIX C: OPTIMIZED ADPCMEncoder(), ADPCMDecoder(), AND TABLE LISTING

```
*****
*   Filename:    ADPCM.C
*****
*   Author:      Rodger Richey
*   Company:    Microchip Technology Incorporated
*   Revision:   0
*   Date:       1-9-96
*   Compiled using Bytecraft Ltd. MPC version BC.193
*****
*   This file contains the ADPCM encode and decode routines. This
*   routines were obtained from the Interactive Multimedia Association's
*   Reference ADPCM algorithm. This algorithm was first implemented by
*   Intel/DVI.
*****
/* Table of index changes */
const int IndexTable[16] = {0xff,0xff,0xff,0xff,2,4,6,8,
                           0xff, 0xff, 0xff, 0xff, 2, 4, 6, 8
};

0005 0782    ADDWF   PCL
0006 34FF    RETLW  FFh
0007 34FF    RETLW  FFh
0008 34FF    RETLW  FFh
0009 34FF    RETLW  FFh
000A 3402    RETLW  02h
000B 3404    RETLW  04h
000C 3406    RETLW  06h
000D 3408    RETLW  08h
000E 34FF    RETLW  FFh
000F 34FF    RETLW  FFh
0010 34FF    RETLW  FFh
0011 34FF    RETLW  FFh
0012 3402    RETLW  02h
0013 3404    RETLW  04h
0014 3406    RETLW  06h
0015 3408    RETLW  08h

/* Quantizer step size lookup table */
const long StepSizeTable[89] = {
    7,8,9,10,11,12,13,14,16,17,19,21,23,25,28,31,34,37,
    41,45,50,55,60,66,73,80,88,97,107,118,130,143,157,
    173,190,209,230,253,279,307,337,371,408,449,494,544,
    598,658,724,796,876,963,1060,1166,1282,1411,1552,
    1707,1878,2066,2272,2499,2749,3024,3327,3660,4026,
    4428,4871,5358,5894,6484,7132,7845,8630,9493,10442,
    11487,12635,13899,15289,16818,18500,20350,22385,
    24623, 27086, 29794, 32767
};

0016 0782    ADDWF   PCL
0017 3407    RETLW  07h
0018 3400    RETLW  00h
0019 3408    RETLW  08h
001A 3400    RETLW  00h
001B 3409    RETLW  09h
001C 3400    RETLW  00h
001D 340A    RETLW  0Ah
001E 3400    RETLW  00h
001F 340B    RETLW  0Bh
0020 3400    RETLW  00h
0021 340C    RETLW  0Ch
0022 3400    RETLW  00h
0023 340D    RETLW  0Dh
0024 3400    RETLW  00h
0025 340E    RETLW  0Eh
0026 3400    RETLW  00h
0027 3410    RETLW  10h
0028 3400    RETLW  00h
0029 3411    RETLW  11h
002A 3400    RETLW  00h
```

002B 3413	RETLW	13h
002C 3400	RETLW	00h
002D 3415	RETLW	15h
002E 3400	RETLW	00h
002F 3417	RETLW	17h
0030 3400	RETLW	00h
0031 3419	RETLW	19h
0032 3400	RETLW	00h
0033 341C	RETLW	1Ch
0034 3400	RETLW	00h
0035 341F	RETLW	1Fh
0036 3400	RETLW	00h
0037 3422	RETLW	22h
0038 3400	RETLW	00h
0039 3425	RETLW	25h
003A 3400	RETLW	00h
003B 3429	RETLW	29h
003C 3400	RETLW	00h
003D 342D	RETLW	2Dh
003E 3400	RETLW	00h
003F 3432	RETLW	32h
0040 3400	RETLW	00h
0041 3437	RETLW	37h
0042 3400	RETLW	00h
0043 343C	RETLW	3Ch
0044 3400	RETLW	00h
0045 3442	RETLW	42h
0046 3400	RETLW	00h
0047 3449	RETLW	49h
0048 3400	RETLW	00h
0049 3450	RETLW	50h
004A 3400	RETLW	00h
004B 3458	RETLW	58h
004C 3400	RETLW	00h
004D 3461	RETLW	61h
004E 3400	RETLW	00h
004F 346B	RETLW	6Bh
0050 3400	RETLW	00h
0051 3476	RETLW	76h
0052 3400	RETLW	00h
0053 3482	RETLW	82h
0054 3400	RETLW	00h
0055 348F	RETLW	8Fh
0056 3400	RETLW	00h
0057 349D	RETLW	9Dh
0058 3400	RETLW	00h
0059 34AD	RETLW	ADh
005A 3400	RETLW	00h
005B 34BE	RETLW	BEh
005C 3400	RETLW	00h
005D 34D1	RETLW	D1h
005E 3400	RETLW	00h
005F 34E6	RETLW	E6h
0060 3400	RETLW	00h
0061 34FD	RETLW	FDh
0062 3400	RETLW	00h
0063 3417	RETLW	17h
0064 3401	RETLW	01h
0065 3433	RETLW	33h
0066 3401	RETLW	01h
0067 3451	RETLW	51h
0068 3401	RETLW	01h
0069 3473	RETLW	73h
006A 3401	RETLW	01h
006B 3498	RETLW	98h
006C 3401	RETLW	01h
006D 34C1	RETLW	C1h
006E 3401	RETLW	01h
006F 34EE	RETLW	EEh

0070	3401	RETLW	01h
0071	3420	RETLW	20h
0072	3402	RETLW	02h
0073	3456	RETLW	56h
0074	3402	RETLW	02h
0075	3492	RETLW	92h
0076	3402	RETLW	02h
0077	34D4	RETLW	D4h
0078	3402	RETLW	02h
0079	341C	RETLW	1Ch
007A	3403	RETLW	03h
007B	346C	RETLW	6Ch
007C	3403	RETLW	03h
007D	34C3	RETLW	C3h
007E	3403	RETLW	03h
007F	3424	RETLW	24h
0080	3404	RETLW	04h
0081	348E	RETLW	8Eh
0082	3404	RETLW	04h
0083	3402	RETLW	02h
0084	3405	RETLW	05h
0085	3483	RETLW	83h
0086	3405	RETLW	05h
0087	3410	RETLW	10h
0088	3406	RETLW	06h
0089	34AB	RETLW	ABh
008A	3406	RETLW	06h
008B	3456	RETLW	56h
008C	3407	RETLW	07h
008D	3412	RETLW	12h
008E	3408	RETLW	08h
008F	34E0	RETLW	E0h
0090	3408	RETLW	08h
0091	34C3	RETLW	C3h
0092	3409	RETLW	09h
0093	34BD	RETLW	BDh
0094	340A	RETLW	0Ah
0095	34D0	RETLW	D0h
0096	340B	RETLW	0Bh
0097	34FF	RETLW	FFh
0098	340C	RETLW	0Ch
0099	344C	RETLW	4Ch
009A	340E	RETLW	0Eh
009B	34BA	RETLW	BAh
009C	340F	RETLW	0Fh
009D	344C	RETLW	4Ch
009E	3411	RETLW	11h
009F	3407	RETLW	07h
00A0	3413	RETLW	13h
00A1	34EE	RETLW	EEh
00A2	3414	RETLW	14h
00A3	3406	RETLW	06h
00A4	3417	RETLW	17h
00A5	3454	RETLW	54h
00A6	3419	RETLW	19h
00A7	34DC	RETLW	DCh
00A8	341B	RETLW	1Bh
00A9	34A5	RETLW	A5h
00AA	341E	RETLW	1Eh
00AB	34B6	RETLW	B6h
00AC	3421	RETLW	21h
00AD	3415	RETLW	15h
00AE	3425	RETLW	25h
00AF	34CA	RETLW	CAh
00B0	3428	RETLW	28h
00B1	34DF	RETLW	DFh
00B2	342C	RETLW	2Ch
00B3	345B	RETLW	5Bh
00B4	3431	RETLW	31h

```

00B5 344B    RETLW  4Bh
00B6 3436    RETLW  36h
00B7 34B9    RETLW  B9h
00B8 343B    RETLW  3Bh
00B9 34B2    RETLW  B2h
00BA 3441    RETLW  41h
00BB 3444    RETLW  44h
00BC 3448    RETLW  48h
00BD 347E    RETLW  7Eh
00BE 344F    RETLW  4Fh
00BF 3471    RETLW  71h
00C0 3457    RETLW  57h
00C1 342F    RETLW  2Fh
00C2 3460    RETLW  60h
00C3 34CE    RETLW  CEh
00C4 3469    RETLW  69h
00C5 3462    RETLW  62h
00C6 3474    RETLW  74h
00C7 34FF    RETLW  FFh
00C8 347F    RETLW  7Fh

002E          signed long diff; /* Difference between sample and
                           predicted sample */
0030          long step;           /* Quantizer step size */
0032          signed long predsample; /* Output of ADPCM predictor */
0034          signed long diffq; /* Dequantized predicted difference */
0036          int index;          /* Index into step size table */

/*************************************************
*      ADPCMEncoder - ADPCM encoder routine
*************************************************
*      Input Variables:
*          signed long sample - 16-bit signed speech sample
*      Return Variable:
*          char - 8-bit number containing the 4-bit ADPCM code
*************************************************/
char ADPCMEncoder( signed long sample )
{
0037
00C9 1283    BCF    STATUS,RPO
00CA 00B7    MOVWF  37
00CB 0804    MOVF   FSR,W
00CC 00B8    MOVWF  38
0039          int code;           /* ADPCM output value */

                           /* Restore previous values of predicted sample and
                           quantizer step size index */
                           predsample = state.prevsample;
00CD 082B    MOVF   2B,W
00CE 00B2    MOVWF  32
00CF 082C    MOVF   2C,W
00D0 00B3    MOVWF  33
00D1 082D    MOVF   2D,W
00D2 00B6    MOVWF  36
00D3 0836    MOVF   36,W
00D4 0084    MOVWF  FSR
00D5 1003    BCF    STATUS,C
00D6 0D84    RLF    FSR
00D7 3000    MOVLW  00h
00D8 008A    MOVWF  PCLATH
00D9 0804    MOVF   FSR,W
00DA 2016    CALL   0016h
00DB 1283    BCF    STATUS,RPO
00DC 00B0    MOVWF  30
00DD 0A84    INCF   FSR
00DE 3000    MOVLW  00h
00DF 008A    MOVWF  PCLATH
00E0 0804    MOVF   FSR,W
00E1 2016    CALL   0016h
00E2 1283    BCF    STATUS,RPO
00E3 00B1    MOVWF  31

```

```
/* Compute the difference between the actual sample
   (sample) and the predicted sample (predsample) */
diff = sample - predsample;

00E4 0832    MOVF   32,W
00E5 0237    SUBWF  37,W
00E6 00AE    MOVWF  2E
00E7 0833    MOVF   33,W
00E8 1C03    BTFSS STATUS,C
00E9 3E01    ADDLW  01h
00EA 0238    SUBWF  38,W
00EB 00AF    MOVWF  2F
00EC 1BAF    BTFSC  2F,7      if(diff >= 0)
00ED 28F0    GOTO   00F0h
00EE 01B9    CLRF   39      code = 0;
00EF 28F9    GOTO   00F9h
else
{
    code = 8;
}
diff = -diff;

00F0 3008    MOVLW  08h
00F1 00B9    MOVWF  39
00F2 09AF    COMF   2F
00F3 09AE    COMF   2E
00F4 0AAE    INCF   2E
00F5 1D03    BTFSS STATUS,Z
00F6 28F9    GOTO   00F9h
00F7 1283    BCF    STATUS,RP0
00F8 0AAF    INCF   2F
}
/* Quantize the difference into the 4-bit ADPCM code
   using the quantizer step size. Inverse quantize
   the ADPCM code into a predicted difference using
   the quantizer step size */
diffq = step >> 3;

00F9 1283    BCF    STATUS,RP0
00FA 0830    MOVF   30,W
00FB 00B4    MOVWF  34
00FC 0831    MOVF   31,W
00FD 00B5    MOVWF  35
00FE 0D35    RLF    35,W
00FF 0CB5    RRF    35
0100 0CB4    RRF    34
0101 0D35    RLF    35,W
0102 0CB5    RRF    35
0103 0CB4    RRF    34
0104 0D35    RLF    35,W
0105 0CB5    RRF    35
0106 0CB4    RRF    34
0107 0830    MOVF   30,W      if( diff >= step )
0108 022E    SUBWF  2E,W
0109 3080    MOVLW  80h
010A 062F    XORWF  2F,W
010B 00A9    MOVWF  29
010C 3080    MOVLW  80h
010D 0631    XORWF  31,W
010E 1C03    BTFSS STATUS,C
010F 3E01    ADDLW  01h
0110 0229    SUBWF  29,W
0111 1C03    BTFSS STATUS,C
0112 2921    GOTO   0121h
0113
0113 1283    BCF    STATUS,RP0      code |= 4;
0114 1539    BSF    39,2
0115 0830    MOVF   30,W      diff -= step;
0116 02AE    SUBWF  2E
0117 0831    MOVF   31,W
0118 1C03    BTFSS STATUS,C
0119 3E01    ADDLW  01h
011A 02AF    SUBWF  2F
011B 0830    MOVF   30,W      diffq += step;
011C 07B4    ADDWF  34
011D 0831    MOVF   31,W
011E 1803    BTFSC  STATUS,C
011F 3E01    ADDLW  01h
```

```

0120 07B5    ADDWF   35
0121 1283    BCF     STATUS,RP0      }
0122 0D31    RLF     31,W
0123 0CB1    RRF     31
0124 0CB0    RRF     30
0125 0830    MOVF    30,W      if( diff >= step )
0126 022E    SUBWF   2E,W
0127 3080    MOVLW   80h
0128 062F    XORWF   2F,W
0129 00A9    MOVWF   29
012A 3080    MOVLW   80h
012B 0631    XORWF   31,W
012C 1C03    BTFSS   STATUS,C
012D 3E01    ADDLW   01h
012E 0229    SUBWF   29,W
012F 1C03    BTFSS   STATUS,C
0130 293F    GOTO    013Fh
0131          {
0131 1283    BCF     STATUS,RP0      code |= 2;
0132 14B9    BSF     39,1
0133 0830    MOVF    30,W      diff -= step;
0134 02AE    SUBWF   2E
0135 0831    MOVF    31,W
0136 1C03    BTFSS   STATUS,C
0137 3E01    ADDLW   01h
0138 02AF    SUBWF   2F
0139 0830    MOVF    30,W      diffq += step;
013A 07B4    ADDWF   34
013B 0831    MOVF    31,W
013C 1803    BTFSC   STATUS,C
013D 3E01    ADDLW   01h
013E 07B5    ADDWF   35
013F 1283    BCF     STATUS,RP0      }
0140 0D31    RLF     31,W
0141 0CB1    RRF     31
0142 0CB0    RRF     30
0143 0830    MOVF    30,W      if( diff >= step )
0144 022E    SUBWF   2E,W
0145 3080    MOVLW   80h
0146 062F    XORWF   2F,W
0147 00A9    MOVWF   29
0148 3080    MOVLW   80h
0149 0631    XORWF   31,W
014A 1C03    BTFSS   STATUS,C
014B 3E01    ADDLW   01h
014C 0229    SUBWF   29,W
014D 1C03    BTFSS   STATUS,C
014E 2957    GOTO    0157h
014F          {
014F 1283    BCF     STATUS,RP0      code |= 1;
0150 1439    BSF     39,0
0151 0830    MOVF    30,W      diffq += step;
0152 07B4    ADDWF   34
0153 0831    MOVF    31,W
0154 1803    BTFSC   STATUS,C
0155 3E01    ADDLW   01h
0156 07B5    ADDWF   35
0157 1283    BCF     STATUS,RP0      }
/* Fixed predictor computes new predicted sample by
   adding the old predicted sample to predicted
   difference */
0158 1DB9    BTFSS   39,3
0159 2961    GOTO    0161h
015A 0834    MOVF    34,W      predsample -= diffq;
015B 02B2    SUBWF   32
015C 0835    MOVF    35,W

```

```
015D 1C03    BTFSS  STATUS,C
015E 3E01    ADDLW  01h
015F 02B3    SUBWF  33
0160 2967    GOTO   0167h      else
0161 0834    MOVF   34,W      predsample += diffq;
0162 07B2    ADDWF   32
0163 0835    MOVF   35,W
0164 1803    BTFSC  STATUS,C
0165 3E01    ADDLW  01h
0166 07B3    ADDWF  33
                                /* Check for overflow of the new predicted sample */
0167 3001    MOVLW  01h
0168 0732    ADDWF  32,W
0169 00A8    MOVWF  28
016A 3080    MOVLW  80h
016B 0633    XORWF 33,W
016C 00A7    MOVWF  27
016D 3000    MOVLW  00h
016E 1803    BTFSC  STATUS,C
016F 3001    MOVLW  01h
0170 0727    ADDWF  27,W
0171 0428    IORWF 28,W
0172 1D03    BTFSS  STATUS,Z
0173 1C03    BTFSS  STATUS,C
0174 297B    GOTO   017Bh
0175 30FF    MOVLW  FFh      predsample = 32767;
0176 1283    BCF    STATUS,RP0
0177 00B2    MOVWF  32
0178 307F    MOVLW  7Fh
0179 00B3    MOVWF  33
017A 2987    GOTO   0187h      else if( predsample < -32768 )
017B 3080    MOVLW  80h      predsample = -32768;
017C 1283    BCF    STATUS,RP0
017D 0633    XORWF 33,W
017E 00A7    MOVWF  27
017F 3000    MOVLW  00h
0180 0227    SUBWF  27,W
0181 1803    BTFSC  STATUS,C
0182 2987    GOTO   0187h
0183 1283    BCF    STATUS,RP0
0184 01B2    CLRF   32
0185 3080    MOVLW  80h
0186 00B3    MOVWF  33
                                /* Find new quantizer stepsize index by adding the
                                 old index to a table lookup using the ADPCM code */
0187 018A    CLRF   PCLATH
0188 1283    BCF    STATUS,RP0
0189 0839    MOVF   39,W
018A 2005    CALL   0005h
018B 1283    BCF    STATUS,RP0
018C 07B6    ADDWF  36
                                /* Check for overflow of the new quantizer step size
                                 index */
018D 1BB6    BTFSC  36,7
018E 01B6    CLRF   36
018F 3080    MOVLW  80h
0190 1283    BCF    STATUS,RP0
0191 0636    XORWF 36,W
0192 00A7    MOVWF  27
0193 30D8    MOVLW  D8h
0194 0227    SUBWF  27,W
0195 1D03    BTFSS  STATUS,Z
0196 1C03    BTFSS  STATUS,C
0197 299B    GOTO   019Bh
0198 3058    MOVLW  58h      index = 88;
0199 1283    BCF    STATUS,RP0
019A 00B6    MOVWF  36
                                /* Save the predicted sample and quantizer step size
                                 index for next iteration */
```

```

019B 1283    BCF    STATUS,RP0      state.prevsample = predsample;
019C 0832    MOVF   32,W
019D 00AB    MOVWF  2B
019E 0833    MOVF   33,W
019F 00AC    MOVWF  2C
01A0 0836    MOVF   36,W      state.previndex = index;
01A1 00AD    MOVWF  2D
                                /* Return the new ADPCM code */
01A2 300F    MOVLW  0Fh      return ( code & 0x0f );
01A3 0539    ANDWF  39,W
01A4 0008    RETURN
}

/*********************************************
*      ADPCMDecoder - ADPCM decoder routine
*****
*      Input Variables:
*          char code - 8-bit number containing the 4-bit ADPCM code
*      Return Variable:
*          signed long - 16-bit signed speech sample
*****/                                signed long ADPCMDecoder(char code )
003A
{
01A5 1283    BCF    STATUS,RP0
01A6 00BA    MOVWF  3A
                                /* Restore previous values of predicted sample and
                                 quantizer step size index */
01A7 082B    MOVF   2B,W      predsample = state.prevsample;
01A8 00B2    MOVWF  32
01A9 082C    MOVF   2C,W
01AA 00B3    MOVWF  33
01AB 082D    MOVF   2D,W      index = state.previndex;
01AC 00B6    MOVWF  36
                                /* Find quantizer step size from lookup table using
                                 index */
01AD 0836    MOVF   36,W      step = StepSizeTable[index];
01AE 0084    MOVWF  FSR
01AF 1003    BCF    STATUS,C
01B0 0D84    RLF    FSR
01B1 3000    MOVLW  00h
01B2 008A    MOVWF  PCLATH
01B3 0804    MOVF   FSR,W
01B4 2016    CALL   0016h
01B5 1283    BCF    STATUS,RP0
01B6 00B0    MOVWF  30
01B7 0A84    INCF   FSR
01B8 3000    MOVLW  00h
01B9 008A    MOVWF  PCLATH
01BA 0804    MOVF   FSR,W
01BB 2016    CALL   0016h
01BC 1283    BCF    STATUS,RP0
01BD 00B1    MOVWF  31
                                /* Inverse quantize the ADPCM code into a difference
                                 using the quantizer step size */
01BE 0830    MOVF   30,W      diffq = step >> 3;
01BF 00B4    MOVWF  34
01C0 0831    MOVF   31,W
01C1 00B5    MOVWF  35
01C2 0D35    RLF   35,W
01C3 0CB5    RRF   35
01C4 0CB4    RRF   34
01C5 0D35    RLF   35,W
01C6 0CB5    RRF   35
01C7 0CB4    RRF   34
01C8 0D35    RLF   35,W
01C9 0CB5    RRF   35
01CA 0CB4    RRF   34
01CB 1D3A    BTFS  3A,2      if( code & 4 )
01CC 29D3    GOTO   01D3h
}

```

```
01CD 0830    MOVF   30,W           diffq += step;
01CE 07B4    ADDWF  34
01CF 0831    MOVF   31,W
01D0 1803    BTFSC STATUS,C
01D1 3E01    ADDLW  01h
01D2 07B5    ADDWF  35
01D3 1283    BCF    STATUS,RP0      if( code & 2 )
01D4 1CBA    BTFSS 3A,1
01D5 29E3    GOTO  01E3h
01D6 0830    MOVF   30,W           diffq += step >> 1;
01D7 00A8    MOVWF  28
01D8 0831    MOVF   31,W
01D9 00A9    MOVWF  29
01DA 0D29    RLF    29,W
01DB 0CA9    RRF    29
01DC 0CA8    RRF    28
01DD 0828    MOVF   28,W
01DE 07B4    ADDWF  34
01DF 0829    MOVF   29,W
01E0 1803    BTFSC STATUS,C
01E1 3E01    ADDLW  01h
01E2 07B5    ADDWF  35
01E3 1283    BCF    STATUS,RP0      if( code & 1 )
01E4 1C3A    BTFSS 3A,0
01E5 29F6    GOTO  01F6h
01E6 0830    MOVF   30,W           diffq += step >> 2;
01E7 00A8    MOVWF  28
01E8 0831    MOVF   31,W
01E9 00A9    MOVWF  29
01EA 0D29    RLF    29,W
01EB 0CA9    RRF    29
01EC 0CA8    RRF    28
01ED 0D29    RLF    29,W
01EE 0CA9    RRF    29
01EF 0CA8    RRF    28
01F0 0828    MOVF   28,W
01F1 07B4    ADDWF  34
01F2 0829    MOVF   29,W
01F3 1803    BTFSC STATUS,C
01F4 3E01    ADDLW  01h
01F5 07B5    ADDWF  35
                                         /* Add the difference to the predicted sample */
01F6 1283    BCF    STATUS,RP0      if( code & 8 )
01F7 1DBA    BTFSS 3A,3
01F8 2A00    GOTO  0200h
01F9 0834    MOVF   34,W           predsample -= diffq;
01FA 02B2    SUBWF 32
01FB 0835    MOVF   35,W
01FC 1C03    BTFSS STATUS,C
01FD 3E01    ADDLW  01h
01FE 02B3    SUBWF 33
01FF 2A06    GOTO  0206h      else
0200 0834    MOVF   34,W           predsample += diffq;
0201 07B2    ADDWF  32
0202 0835    MOVF   35,W
0203 1803    BTFSC STATUS,C
0204 3E01    ADDLW  01h
0205 07B3    ADDWF  33
                                         /* Check for overflow of the new predicted sample */
0206 3001    MOVLW 01h
0207 0732    ADDWF  32,W
0208 00A8    MOVWF  28
0209 3080    MOVLW 80h
020A 0633    XORWF 33,W
020B 00A7    MOVWF  27
020C 3000    MOVLW 00h
020D 1803    BTFSC STATUS,C
020E 3001    MOVLW 01h
020F 0727    ADDWF  27,W
```

```

0210 0428 IORWF 28,W
0211 1D03 BTFSS STATUS,Z
0212 1C03 BTFSS STATUS,C
0213 2A1A GOTO 021Ah
0214 30FF MOVLW FFh           predsample = 32767;
0215 1283 BCF STATUS,RP0
0216 00B2 MOVWF 32
0217 307F MOVLW 7Fh
0218 00B3 MOVWF 33
0219 2A26 GOTO 0226h         else if( predsample < -32768 )
021A 3080 MOVLW 80h          predsample = -32768;
021B 1283 BCF STATUS,RP0
021C 0633 XORWF 33,W
021D 00A7 MOVWF 27
021E 3000 MOVLW 00h
021F 0227 SUBWF 27,W
0220 1803 BTFSC STATUS,C
0221 2A26 GOTO 0226h
0222 1283 BCF STATUS,RP0
0223 01B2 CLRF 32
0224 3080 MOVLW 80h
0225 00B3 MOVWF 33

                                         /* Find new quantizer step size by adding the old
                                         index and a table lookup using the ADPCM code */
0226 018A CLRF PCLATH
0227 1283 BCF STATUS,RP0
0228 083A MOVF 3A,W
0229 2005 CALL 0005h
022A 1283 BCF STATUS,RP0
022B 07B6 ADDWF 36

                                         /* Check for overflow of the new quantizer step size
                                         index */
022C 1BB6 BTFSC 36,7
022D 01B6 CLRF 36
022E 3080 MOVLW 80h
022F 1283 BCF STATUS,RP0
0230 0636 XORWF 36,W
0231 00A7 MOVWF 27
0232 30D8 MOVLW D8h
0233 0227 SUBWF 27,W
0234 1D03 BTFSS STATUS,Z
0235 1C03 BTFSS STATUS,C
0236 2A3A GOTO 023Ah
0237 3058 MOVLW 58h          index = 88;
0238 1283 BCF STATUS,RP0
0239 00B6 MOVWF 36

                                         /* Save predicted sample and quantizer step size
                                         index for next iteration */
023A 1283 BCF STATUS,RP0
023B 0832 MOVF 32,W
023C 00AB MOVWF 2B
023D 01AC CLRF 2C
023E 1BAB BTFSC 2B,7
023F 03AC DECF 2C
0240 1283 BCF STATUS,RP0
0241 0836 MOVF 36,W
0242 00AD MOVWF 2D
                                         state.previndex = index;

                                         /* Return the new speech sample */
0243 0833 MOVF 33,W
0244 0084 MOVWF FSR
0245 0832 MOVF 32,W
0246 0008 RETURN
}

```

APPENDIX D: INTERACTIVE MULTIMEDIA ASSOCIATION INFORMATION

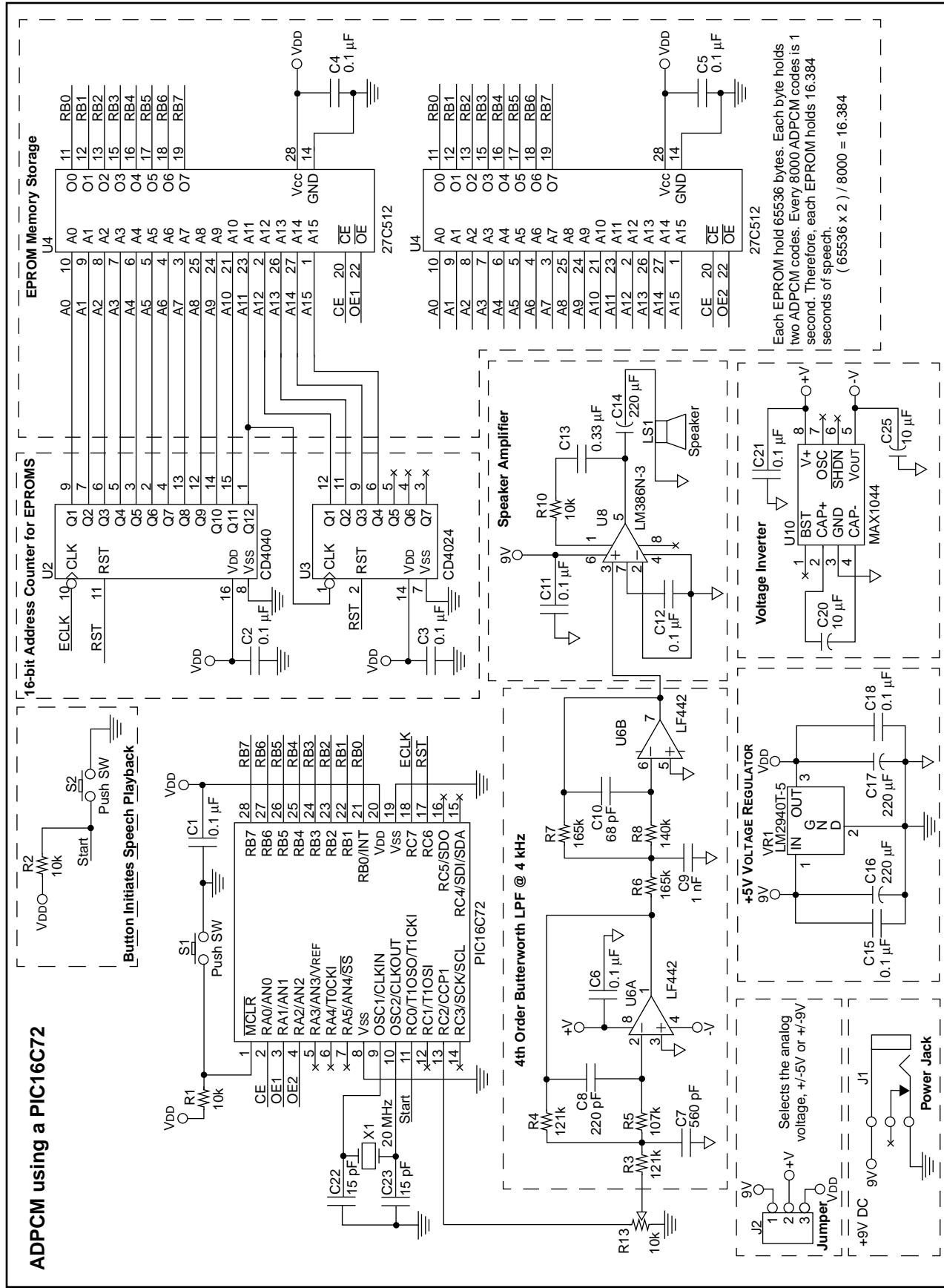
The IMA ADPCM Reference Algorithm is contained in the Digital Audio Doc-Pac. The Doc-Pac contains the following information:

- *About IMA Digital Audio* - describes the IMA's activities in digital audio
- *IMA Recommended Practices for Enhancing Digital Audio Compatability in Multimedia Systems* (version 3.0). This document contains the official technical recommendations including the ADPCM algorithm
- *IMA Digital Audio Special Edition Proceedings* This document contains a detailed notes of the evaluation process, code fragments and testing methodologies.
- Floppy disk with code fragments.
- Contact information for companies supporting IMA ADPCM.

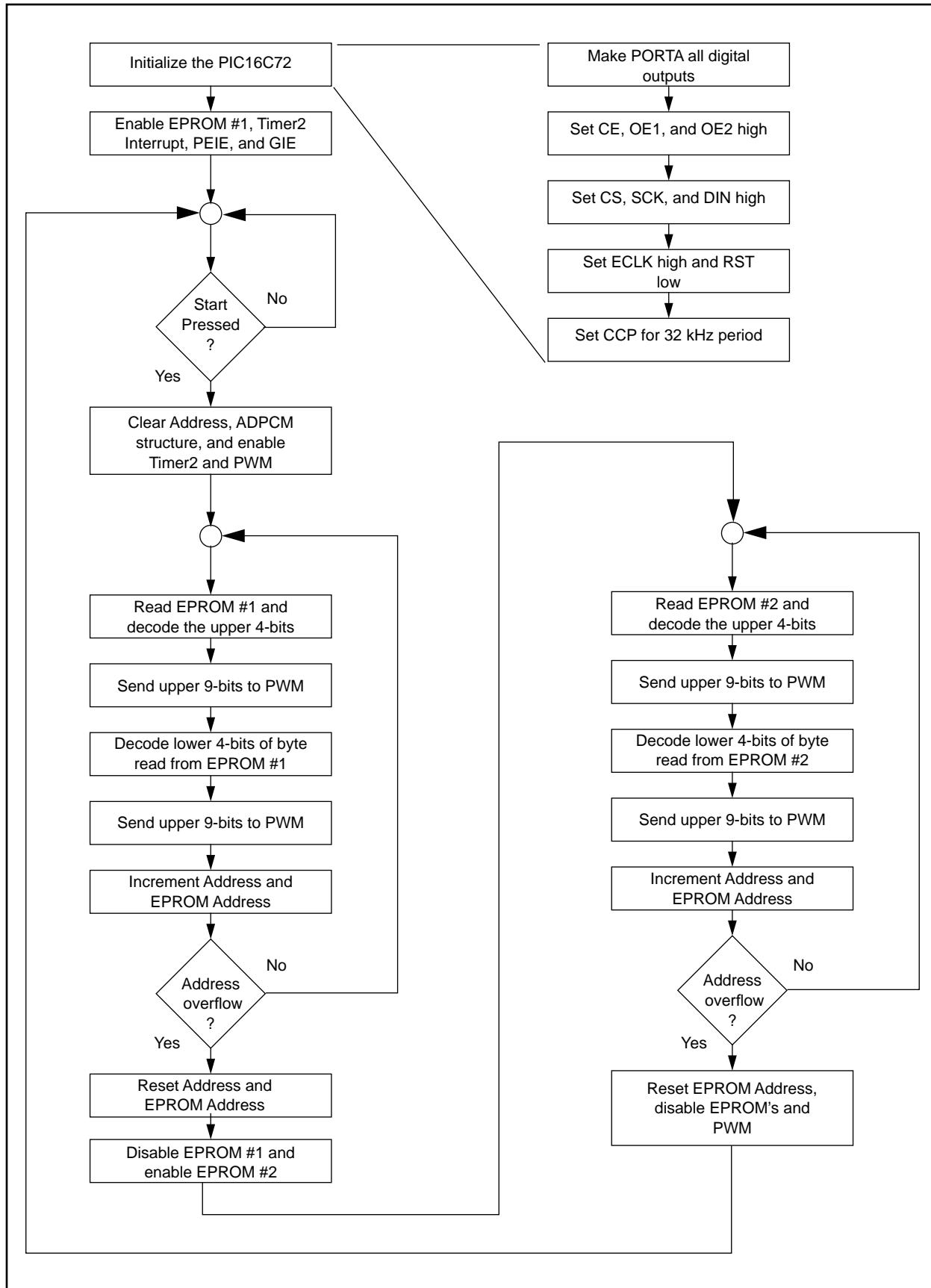
The IMA can be reached at:

Interactive Multimedia Association
48 Maryland Avenue, Suite 202
Annapolis, MD 21401-8011 USA
Tel: (410)-626-1380
Fax: (410)-263-0590
<http://www.ima.org>

APPENDIX E: APPLICATION HARDWARE SCHEMATIC



APPENDIX F: APPLICATION FIRMWARE BLOCK DIAGRAM AND LISTING



Firmware Listing

```
*****
*   Filename:   SPEECH.C
*****
*   Author:     Rodger Richey
*   Title:      Senior Applications Engineer
*   Company:    Microchip Technology Incorporated
*   Revision:   0
*   Date:       1-9-96
*   Compiled using Bytecraft Ltd. MPC version BC.193
*****
*   Include files:
*       16c72.h - Standard include file for the PIC16C72 device
*       delay14.h - Standard include file for delay routines
*       adpcm.h - Include file with ADPCM related information (Rev0)
*       adpcm.c - Source file with ADPCM routines (Rev0)
*****
*   This file contains the routines to:
*       - Initialize the PIC16C72
*       - Read data from the EPROMs
*       - Call the ADPCM decoder routine
*       - Send data to the DAC and PWM
*       - Increment the address of the EPROMs
*****
*   External Clock Frequency: 20MHz
*   Configuration Bit Settings
*       OSC:      HS
*       WDT:     Off
*       PWRTE:   On
*       CP:      Off
*   Compression and Decompression (only Decompression is used)
*       Program Memory Usage:    906 words
*       Data Memory Usage:       24 bytes
*   Compression only
*       Program Memory Usage:    686 words
*       Data Memory Usage:       22 bytes
*****
#pragma option v
#include <16c72.h>
#pragma option +l;
#define MAXROM 2043
0FFB          #pragma memory ROM [MAXROM] @ 0x05;
0005 0FFB      #pragma memory RAM [0x96]   @ 0x20;
0020 0060      #pragma memory RAM [0x32]   @ 0xA0;
00A0 0060      #pragma option +l;

#include "adpcm.h"
*****
*   Filename:   PCADPCM.H
*****
*   Author:     Rodger Richey
*   Title:      Senior Applications Engineer
*   Company:    Microchip Technology Incorporated
*   Revision:   0
*   Date:       1-11-96
*   Compiled using Bytecraft Ltd. MPC version BC.193
*****
*   This is the header file that contains the ADPCM structure definition
*   and the function prototypes.
*****
struct ADPCMState {
    signed long prevsample;      /* Predicted sample */
    int         previndex; /*Index into step size table*/
};
```

```
/* Function prototype for the ADPCM Encoder routine */
signed long ADPCMDecoder( char );

/* Function prototype for the ADPCM Decoder routine */
char ADPCMEncoder( signed long );

// Defines for PORTA
0000 #define CE 0 // Chip Enable for EPROMS
0001 #define OE1 1 // Output Enable for EEPROM #1
0002 #define OE2 2 // Output Enable for EEPROM #2

// Defines for PORTC
0000 #define STRT 0 // Start Button input
0002 #define PWM 2 // PWM output
0006 #define RST 6 // EEPROM counter reset
0007 #define ECLK 7 // EEPROM counter clock

0025 unsigned long Address; // EEPROM address
002A unsigned char Wait;
002B 0003 struct ADPCMState state;// ADPCM structure

#include "adpcm.c"
```

-----Insert Appendix C here-----

```
*****
*   Init72 - This function initializes PORTA, PORTC, and PWM
*****
*   Input Variables:
*       None
*   Return Variables:
*       None
*****
void Init72(void)
{
    OPTION = 8;

0247 3008 MOVLW 08h
0248 1683 BSF STATUS,RP0
0249 0081 MOVWF TMR0
024A 3007 MOVLW 07h      ADCON1 = 7; // Make PORTA all digital
024B 009F MOVWF ADCON0
024C 1283 BCF STATUS,RP0      PORTA = 7; // Set CE,OE1,OE2
024D 0085 MOVWF PORTA
024E 1683 BSF STATUS,RP0      TRISA = 0; // Make PORTA all outputs
024F 0185 CLRF PORTA
0250 3040 MOVLW 40h      PORTC = 0x40; // Set ECLK, all outputs
0251 1283 BCF STATUS,RP0
0252 0087 MOVWF PORTC
0253 3005 MOVLW 05h      TRISC = 0x05; // Clear RST output, STRT input
0254 1683 BSF STATUS,RP0
0255 0087 MOVWF PORTC
0256 309B MOVLW 9Bh      PR2 = 155; // Set PWM for 32kHz period
0257 0092 MOVWF T2CON
0258 1283 BCF STATUS,RP0      CCPR1L = 0;
0259 0195 CLRF CCPR1L
025A 3018 MOVLW 18h      T2CON = 0x18; // Set Timer2 postscaler to 4
025B 0092 MOVWF T2CON
025C 0008 RETURN      return;
}

*****
*   main - This function controls everything, kinda like a god.
*****
*   Input Variables:
```

```

*      None
*      Return Variables:
*      None
*****
void main(void)
{
003B                                char code;           // EEPROM byte
003C                                signed long sample; // decoded sample
003E                                unsigned long pwmout; // temporary variable for PWM

025D 2247    CALL   0247h          Init72();           // Initialize the PIC16C72

025E 3001    MOVLW  01h            Wait = 1;
025F 1283    BCF    STATUS,RP0
0260 00AA    MOVWF  2A
0261 1707    BSF    PORTC,6       PORTC.RST = 1;      // Reset the EEPROM counter
0262 0000    NOP
0263 0000    NOP
0264 1307    BCF    PORTC,6       PORTC.RST = 0;
0265 0000    NOP
0266 0000    NOP
0267 1085    BCF    PORTA,1       PORTA.OE1 = 0;      // Enable EEPROM #1
0268 0000    NOP
0269 0000    NOP
026A 1005    BCF    PORTA,0       PORTA.CE = 0;
026B 0000    NOP
026C 0000    NOP
026D 108C    BCF    PIR1,1        PIR1.TMR2IF = 0;     // Enable Timer2 Interrupts
026E 1683    BSF    STATUS,RP0
026F 148C    BSF    PIR1,1
0270 170B    BSF    INTCON,PEIE  INTCON.PEIE = 1;      // Enable PEIE and GIE
0271 178B    BSF    INTCON,GIE
                                         INTCON.GIE = 1;

                                         while(1)
                                         {
0272 1283    BCF    STATUS,RP0
0273 1807    BTFSC  PORTC,0
0274 2A72    GOTO   0272h
0275                                while(PORTC.SRTT); // Wait for Start button to be
0275 1283    BCF    STATUS,RP0
                                         while(!PORTC.SRTT); // pressed then released
0276 1C07    BTFSS  PORTC,0
0277 2A75    GOTO   0275h
0278 1283    BCF    STATUS,RP0       Address = 0;        // Clear EEPROM address
0279 01A5    CLRF   25
027A 01A6    CLRF   26
027B 01AB    CLRF   2B
                                         state.prevsample = 0; // Clear ADPCM structure
027C 01AC    CLRF   2C
027D 01AD    CLRF   2D
                                         state.previndex = 0;

027E 1683    BSF    STATUS,RP0       TRISC.PWM = 0;      // Make PWM an output
027F 1107    BCF    PORTC,2
0280 1283    BCF    STATUS,RP0       T2CON.TMR2ON = 1; // Enable Timer2
0281 1512    BSF    T2CON,2
0282 300F    MOVLW  0Fh            CCP1CON = 0x0f;      // Enable PWM
0283 0097    MOVWF  CCP1CON
                                         do                  // Decode upper 4 bits of code
                                         {
0284 1283    BCF    STATUS,RP0       code = PORTB;
0285 0806    MOVF   PORTB,W
0286 00BB    MOVWF  3B
0287 083B    MOVF   3B,W           sample = ADPCMDecoder( (code>>4)&0x0f );
0288 00A7    MOVWF  27
0289 0EA7    SWAPF  27
028A 300F    MOVLW  0Fh
028B 0527    ANDWF  27,W
028C 390F    ANDLW  0Fh

```

```
028D 21A5    CALL    01A5h
028E 1283    BCF     STATUS,RP0
028F 00BC    MOVWF   3C
0290 0804    MOVF    FSR,W
0291 00BD    MOVWF   3D
0292 1283    BCF     STATUS,RP0      while(Wait); // Wait for 8kHz to output
0293 082A    MOVF    2A,W
0294 3800    IORLW   00h
0295 1D03    BTFSS   STATUS,Z
0296 2A92    GOTO    0292h
0297 3001    MOVLW   01h      Wait = 1;
0298 1283    BCF     STATUS,RP0
0299 00AA    MOVWF   2A
029A 083C    MOVF    3C,W      pwmout = sample; // Write to PWM
029B 00BE    MOVWF   3E
029C 083D    MOVF    3D,W
029D 00BF    MOVWF   3F
029E 1FB0    BTFSS   3D,7      if(sample<0) // Add offset to
029F 2AA4    GOTO    02A4h
02A0 3080    MOVLW   80h      pwmout -= 0x8000; // sample
02A1 023F    SUBWF   3F,W
02A2 00BF    MOVWF   3F
02A3 2AA6    GOTO    02A6h
02A4 3080    MOVLW   80h      else
02A5 07BF    ADDWF   3F      pwmout += 0x8000;
02A6 083F    MOVF    3F,W      CCPR1L = (pwmout>>9)&0x007f; // Write 7 bits
02A7 00A7    MOVWF   27
02A8 0CA7    RRF     27
02A9 307F    MOVLW   7Fh
02AA 0527    ANDWF   27,W
02AB 0095    MOVWF   CCPR1L
02AC 30CF    MOVLW   CFh      CCP1CON &= 0xcf; // to CCPR1L
02AD 0597    ANDWF   CCP1CON
02AE 183F    BTFSC   3F,0      if(pwmout&0x0100) // Write 2 bits
02AF 1697    BSF     CCP1CON,5  CCP1CON.5 = 1; // to CCP1CON
02B0 1283    BCF     STATUS,RP0  if(pwmout&0x0080) // to get 9-bit
02B1 1BBE    BTFSC   3E,7
02B2 1617    BSF     CCP1CON,4  CCP1CON.4 = 1; // PWM

                                         // Decode lower 4 bits of code
02B3 300F    MOVLW   0Fh      sample = ADPCMDecoder(code&0x0f);
02B4 1283    BCF     STATUS,RP0
02B5 053B    ANDWF   3B,W
02B6 118A    BCF     PCLATH,3
02B7 21A5    CALL    01A5h
02B8 118A    BCF     PCLATH,3
02B9 1283    BCF     STATUS,RP0
02BA 00BC    MOVWF   3C
02BB 0804    MOVF    FSR,W
02BC 00BD    MOVWF   3D
02BD 1283    BCF     STATUS,RP0      while(Wait); // Wait for 8kHz to output
02BE 082A    MOVF    2A,W
02BF 3800    IORLW   00h
02C0 1D03    BTFSS   STATUS,Z
02C1 2ABD    GOTO    02Bdh
02C2 3001    MOVLW   01h      Wait = 1;
02C3 1283    BCF     STATUS,RP0
02C4 00AA    MOVWF   2A
02C5 083C    MOVF    3C,W      pwmout = sample; // Write to PWM
02C6 00BE    MOVWF   3E
02C7 083D    MOVF    3D,W
02C8 00BF    MOVWF   3F
02C9 1FB0    BTFSS   3D,7      if(sample<0) // Add offset to
02CA 2ACF    GOTO    02CFh
02CB 3080    MOVLW   80h      pwmout -= 0x8000; // sample
02CC 023F    SUBWF   3F,W
```

```

02CD 00BF    MOVWF  3F
02CE 2AD1    GOTO   02D1h
02CF 3080    MOVLW  80h
02D0 07BF    ADDWF   3F
02D1 083F    MOVF   3F,W
02D2 00A7    MOVWF  27
02D3 0CA7    RRF    27
02D4 307F    MOVLW  7Fh
02D5 0527    ANDWF  27,W
02D6 0095    MOVWF  CCPR1L
02D7 30CF    MOVLW  CFh
02D8 0597    ANDWF  CCP1CON
02D9 183F    BTFSC  3F,0
02DA 1697    BSF    CCP1CON,5
02DB 1283    BCF    STATUS,RP0
02DC 1BBE    BTFSC  3E,7
02DD 1617    BSF    CCP1CON,4

                                         CCP1CON &= 0xcf;           // to CCPR1L
                                         if(pwmout&0x0100)        // Write 2 bits
                                         CCP1CON.5 = 1;          // to CCP1CON
                                         if(pwmout&0x0080)        // to get 9-bit
                                         CCP1CON.4 = 1;          // PWM

                                         // Increment Address of EPROMS
                                         Address++;

02DE 1283    BCF    STATUS,RP0
02DF 0AA5    INCF   25
02E0 1903    BTFSC  STATUS,Z
02E1 0AA6    INCF   26
02E2 1787    BSF    PORTC,7
02E3 0000    NOP
02E4 0000    NOP
02E5 1387    BCF    PORTC,7
02E6 0000    NOP
02E7 0000    NOP
02E8 0826    MOVF   26,W
02E9 0425    IORWF  25,W
02EA 118A    BCF    PCLATH,3
02EB 1D03    BTFSS  STATUS,Z
02EC 2A84    GOTO   0284h

02ED 1283    BCF    STATUS,RP0
02EE 1405    BSF    PORTA,0
02EF 0000    NOP
02F0 0000    NOP
02F1 1485    BSF    PORTA,1
02F2 0000    NOP
02F3 0000    NOP
02F4 1705    BSF    PORTA,6
02F5 0000    NOP
02F6 0000    NOP
02F7 1305    BCF    PORTA,6
02F8 0000    NOP
02F9 0000    NOP
02FA 1105    BCF    PORTA,2
02FB 0000    NOP
02FC 0000    NOP
02FD 1005    BCF    PORTA,0
02FE 0000    NOP
02FF 0000    NOP
0300 01A5    CLRF   25
0301 01A6    CLRF   26
0302 0000    NOP
0303 0000    NOP

                                         PORTA.CE = 1;           // Disable EPROM #1
                                         NOP();
                                         NOP();
                                         PORTA.OE1 = 1;
                                         NOP();
                                         NOP();
                                         NOP();
                                         PORTA.RST = 1;         // Reset EPROM counter
                                         NOP();
                                         NOP();
                                         PORTA.RST = 0;
                                         NOP();
                                         NOP();
                                         NOP();
                                         PORTA.OE2 = 0;         // Enable EPROM #2
                                         NOP();
                                         NOP();
                                         PORTA.CE = 0;
                                         NOP();
                                         NOP();
                                         NOP();
                                         Address = 0;           // Clear EPROM Address
                                         NOP();
                                         NOP();

                                         do
                                         {
                                         code = PORTB;           // Decode upper 4 bits of code
                                         sample = ADPCMDecoder( (code>>4)&0x0f );

```

```
0309 0EA7 SWAPF 27
030A 300F MOVLW 0Fh
030B 0527 ANDWF 27,W
030C 390F ANDLW 0Fh
030D 21A5 CALL 01A5h
030E 1283 BCF STATUS,RP0
030F 00BC MOVWF 3C
0310 0804 MOVF FSR,W
0311 00BD MOVWF 3D
0312 1283 BCF STATUS,RP0      while(Wait); // Wait for 8kHz
0313 082A MOVF 2A,W
0314 3800 IORLW 00h
0315 1D03 BTFSS STATUS,Z
0316 2B12 GOTO 0312h
0317 3001 MOVLW 01h      Wait = 1;
0318 1283 BCF STATUS,RP0
0319 00AA MOVWF 2A
031A 083C MOVF 3C,W      pwmout = sample; // Write to PWM
031B 00BE MOVWF 3E
031C 083D MOVF 3D,W
031D 00BF MOVWF 3F
031E 1FB3 BTFSS 3D,7      if(sample<0) // Add offset to
031F 2B24 GOTO 0324h
0320 3080 MOVLW 80h      pwmout -= 0x8000; // sample
0321 023F SUBWF 3F,W
0322 00BF MOVWF 3F
0323 2B26 GOTO 0326h
0324 3080 MOVLW 80h      else
0325 07BF ADDWF 3F      pwmout += 0x8000;
0326 083F MOVF 3F,W      CCPR1L = (pwmout>>9)&0x007f; // Write 7 bits
0327 00A7 MOVWF 27
0328 0CA7 RRF 27
0329 307F MOVLW 7Fh
032A 0527 ANDWF 27,W
032B 0095 MOVWF CCPR1L
032C 30CF MOVLW CFh      CCP1CON &= 0xcf; // to CCPR1L
032D 0597 ANDWF CCP1CON
032E 183F BTFSC 3F,0      if(pwmout&0x0100) // Write 2 bits
032F 1697 BSF CCP1CON,5      CCP1CON.5 = 1; // to CCP1CON
0330 1283 BCF STATUS,RP0      if(pwmout&0x0080) // to get 9-bit
0331 1BBE BTFSC 3E,7
0332 1617 BSF CCP1CON,4      CCP1CON.4 = 1; // PWM

                                         // Decode lower 4 bits of code
0333 300F MOVLW 0Fh      sample = ADPCMDecoder(code&0x0f);
0334 1283 BCF STATUS,RP0
0335 053B ANDWF 3B,W
0336 118A BCF PCLATH,3
0337 21A5 CALL 01A5h
0338 118A BCF PCLATH,3
0339 1283 BCF STATUS,RP0
033A 00BC MOVWF 3C
033B 0804 MOVF FSR,W
033C 00BD MOVWF 3D
033D 1283 BCF STATUS,RP0      while(Wait); // Wait for 8kHz
033E 082A MOVF 2A,W
033F 3800 IORLW 00h
0340 1D03 BTFSS STATUS,Z
0341 2B3D GOTO 033Dh
0342 3001 MOVLW 01h      Wait = 1;
0343 1283 BCF STATUS,RP0
0344 00AA MOVWF 2A
0345 083C MOVF 3C,W      pwmout = sample; // Write to PWM
0346 00BE MOVWF 3E
0347 083D MOVF 3D,W
0348 00BF MOVWF 3F
```

```

0349 1FB0    BTFSS  3D,7           if(sample<0)      // Add offset to
034A 2B4F    GOTO   034Fh
034B 3080    MOVLW  80h          pwmout -= 0x8000; // sample
034C 023F    SUBWF  3F,W
034D 00BF    MOVWF  3F
034E 2B51    GOTO   0351h
034F 3080    MOVLW  80h          else
0350 07BF    ADDWF  3F
0351 083F    MOVF   3F,W        CCPR1L = (pwmout>>9)&0x007f; // Write 7 bits
0352 00A7    MOVWF  27
0353 0CA7    RRF    27
0354 307F    MOVLW  7Fh
0355 0527    ANDWF  27,W
0356 0095    MOVWF  CCPR1L
0357 30CF    MOVLW  CFh          CCP1CON &= 0xcf;           // to CCPR1L
0358 0597    ANDWF  CCP1CON
0359 183F    BTFSC  3F,0          if(pwmout&0x0100)      // Write 2 bits
035A 1697    BSF    CCP1CON,5    CCP1CON.5 = 1;           // to CCP1CON
035B 1283    BCF    STATUS,RP0    if(pwmout&0x0080)      // to get 9-bit
035C 1BBE    BTFSC  3E,7
035D 1617    BSF    CCP1CON,4    CCP1CON.4 = 1;           // PWM

                                                // Increment Address of EPROMS
035E 1283    BCF    STATUS,RP0    Address++;
035F 0AA5    INCF   25
0360 1903    BTFSC  STATUS,Z
0361 0AA6    INCF   26
0362 1787    BSF    PORTC,7     PORTC.ECLK = 1;
0363 0000    NOP
0364 0000    NOP
0365 1387    BCF    PORTC,7     PORTC.ECLK = 0;
0366 0000    NOP
0367 0000    NOP
0368 0826    MOVF   26,W          } while(Address); // Has Address overflowed?
0369 0425    IORWF  25,W
036A 118A    BCF    PCLATH,3
036B 1D03    BTFSS  STATUS,Z
036C 2B04    GOTO   0304h
036D 1283    BCF    STATUS,RP0    T2CON.TMR2ON = 0; // Disable Timer2
036E 1112    BCF    T2CON,2
036F 0197    CLRF   CCP1CON    CCP1CON = 0;           // Disable PWM
0370 1683    BSF    STATUS,RP0    TRISC.PWM = 1;       // Make PWM input
0371 1507    BSF    PORTC,2
0372 1283    BCF    STATUS,RP0    PORTA.CE = 1;       // Disable EPROM #2
0373 1405    BSF    PORTA,0
0374 0000    NOP
0375 0000    NOP
0376 1505    BSF    PORTA,2     PORTA.OE2 = 1;
0377 0000    NOP
0378 0000    NOP
0379 1705    BSF    PORTA,6     PORTA.RST = 1;       // Reset EPROM counter
037A 0000    NOP
037B 0000    NOP
037C 1305    BCF    PORTA,6     PORTA.RST = 0;
037D 0000    NOP
037E 0000    NOP
037F 1085    BCF    PORTA,1     PORTA.OE1 = 0;       // Enable EPROM #1
0380 0000    NOP
0381 0000    NOP
0382 1005    BCF    PORTA,0     PORTA.CE = 0;
0383 2A72    GOTO   0272h
0384 0008    RETURN
}

/****************************************
*      __INT - This is the interrupt service routine. Only Timer 2 overflow      *
*      is implemented.                                                       *
****************************************

```

```
*****
*      Input Variables:          *
*          None                  *
*      Return Variables:         *
*          None                  *
*****/
```

0004 2B85 GOTO 0385h void __INT(void)
0385 {
0385 1283 BCF STATUS,RP0 if(PIR1.TMR2IF) // Timer2 overflow interrupt
0386 1C8C BTFSS PIR1,1
0387 2B8A GOTO 038Ah
0388 {
0388 01AA CLRF 2A Wait = 0;
0389 108C BCF PIR1,1 PIR1.TMR2IF = 0; // Clear flag
038A 0009 RETFIE }
 return;
}

ROM USAGE MAP

0000 to 0002 0004 to 038A
Total ROM used 038A

Errors : 0
Warnings : 0

APPENDIX G: PC ADPCM ENCODER/DECODER PROGRAM

PCSPEECH.C

```
*****
*      Filename: PCSPEECH.C
*****
*      Author:      Rodger Richey
*      Title:      Senior Applications Engineer
*      Company:    Microchip Technology Incorporated
*      Revision:   0
*      Date:       1-11-96
*      Compiled using Borland C+ Version 3.1
*****
*      Include files:
*          stdio.h - Standard input/output header file
*          stdlib.h - Standard library header file
*          string.h - Standard string header file
*          pcadpcm.h - ADPCM related information header file (Rev0)
*****
*      Usage:
*          ADPCM Encode - pcspeech e <infile> <outfile>
*                          <infile> is a 16-bit raw speech file
*                          <outfile> contains the ADPCM codes
*          ADPCM Decode - pcspeech d <infile> <outfile>
*                          <infile> contains the ADPCM codes
*                          <outfile> is a 16-bit raw speech file
*****
*      This file contains the code to:
*          - Open the input and output files
*          - Read data from the input file
*          - Call the encode/decode routines
*          - Write data to the output file
*****
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "pcadpcm.h"

*****
*      Usage - this routine prints a how to message for the pcspeech prgm
*****
*      Input variables:
*          None
*      Output variables:
*          None
*****
void Usage(void)
{
    printf("ADPCM Encoder/Decoder -- usage:\n");
    printf("\tEncoder = pcspeech e infile outfile\n");
    printf("\tDecoder = pcspeech d infile outfile\n");
    exit(1);
}

*****
*      main - controls file I/O and ADPCM calls
*****
*      Input variables:
*          int argc - number of arguments in argv
*          char **argv - pointer to an array of strings
*      Return variables:
*          None
*****
void main(
    int    argc,
    char  **argv)
```

```
{  
    int      which;  
    short      sample;  
    unsigned char   code;  
    int      n;  
    struct ADPCMstate   state;  
    FILE      *fpin;  
    FILE      *fpout;  
  
    state.prevsample=0;  
    state.previndex=0;  
  
    /* Determine if this is an encode or decode operation */  
    if(argc <= 1)  
        Usage();  
    else if( strcmp(argv[1],"e")==0 || strcmp(argv[1],"E")==0 )  
        which = 0;  
    else if( strcmp(argv[1],"d")==0 || strcmp(argv[1],"D")==0 )  
        which = 1;  
    argc--;  
    argv++;  
  
    /* Open input file for processing */  
    if(argc <= 1)  
        Usage();  
    else if( (fpin=fopen(argv[1],"rb"))==NULL )  
    {  
        printf("ADPCM Encoder/Decoder\n");  
        printf("ERROR: Could not open %s for input\n",argv[1]);  
        exit(1);  
    }  
    argc--;  
    argv++;  
  
    /* Open output file */  
    if(argc <= 1)  
    {  
        fclose(fpin);  
        Usage();  
    }  
    else if( (fpout=fopen(argv[1],"wb"))==NULL )  
    {  
        fclose(fpin);  
        printf("ADPCM Encoder/Decoder\n");  
        printf("ERROR: Could not open %s for output\n",argv[1]);  
        exit(1);  
    }  
  
    // ADPCM Decoder selected  
    if(which)  
    {  
        printf("ADPCM Decoding in progress\n");  
        /* Read and unpack input codes and process them */  
        while (fread(&code, sizeof (char), 1, fpin) == 1)  
        {  
            // Send the upper 4-bits of code to decoder  
            sample = ADPCMDecoder((code>>4)&0x0f, &state);  
            // Write sample for upper 4-bits of code  
            fwrite(&sample, sizeof(short), 1, fpout);  
  
            // Send the lower 4-bits of code to decoder  
            sample = ADPCMDecoder(code&0x0f,&state);  
            // Write sample for lower 4-bits of code  
            fwrite(&sample,sizeof(short),1,fpout);  
        }  
    }  
}
```

```

// ADPCM Encoder selected
else
{
    printf("ADPCM Encoding in progress\n");
    /* Read input file and process */
    while (fread(&sample, sizeof(short), 1, fpin) == 1)
    {
        // Encode sample into lower 4-bits of code
        code = ADPCMEncoder(sample,&state);
        // Move ADPCM code to upper 4-bits
        code = (code << 4) & 0xf0;
        // Read new sample from file
        if(fread(&sample,sizeof(short),1,fpin)==0)
        {
            // No more samples, write code to file
            fwrite(&code,sizeof(char),1,fpout);
            break;
        }
        // Encode sample and save in lower 4-bits of code
        code |= ADPCMEncoder(sample,&state);
        // Write code to file, code contains 2 ADPCM codes
        fwrite(&code, sizeof (char), 1, fpout);
    }
}
fclose(fpin);
fclose(fpout);
}

```

PCADPCM.H

```

/****************************************************************************
*      Filename: PCADPCM.H
*****
*      Author:      Rodger Richey
*      Title:      Senior Applications Engineer
*      Company:     Microchip Technology Incorporated
*      Revision:    0
*      Date:       1-11-96
*      Compiled using Borland C+ Version 3.1
*****
*      This is the header file that contains the ADPCM structure definition
*      and the function prototypes.
*****
struct ADPCMstate {
    short prevsample; /* Predicted sample */
    int previndex; /* Index into step size table */
};

/* Function prototype for the ADPCM Encoder routine */
char ADPCMEncoder(short , struct ADPCMstate *);

/* Function prototype for the ADPCM Decoder routine */
int ADPCMDecoder(char , struct ADPCMstate *);

```

PCADPCM.C

```

/****************************************************************************
*      Filename: PCADPCM.C
*****
*      Author:      Rodger Richey
*      Title:      Senior Applications Engineer
*      Company:     Microchip Technology Incorporated
*      Revision:    0
*      Date:       1-11-96
*      Compiled using Borland C+ Version 3.1
*****
```

```
*****
*      Include files:                                *
*          stdio.h - Standard input/output header file   *
*          pcadpcm.h - ADPCM related information header file (Rev0)   *
*****
*      This file contains the ADPCM encode and decode routines. These      *
*      routines were obtained from the Interactive Multimedia Association's  *
*      Reference ADPCM algorithm. This algorithm was first implemented by   *
*      Intel/DVI.                                         *
*****/
```

```
#include <stdio.h>
#include "pcadpcm.h"

/* Table of index changes */
signed char IndexTable[16] = {
    -1, -1, -1, -1, 2, 4, 6, 8,
    -1, -1, -1, -1, 2, 4, 6, 8,
};

/* Quantizer step size lookup table */
int StepSizeTable[89] = {
    7, 8, 9, 10, 11, 12, 13, 14, 16, 17,
    19, 21, 23, 25, 28, 31, 34, 37, 41, 45,
    50, 55, 60, 66, 73, 80, 88, 97, 107, 118,
    130, 143, 157, 173, 190, 209, 230, 253, 279, 307,
    337, 371, 408, 449, 494, 544, 598, 658, 724, 796,
    876, 963, 1060, 1166, 1282, 1411, 1552, 1707, 1878, 2066,
    2272, 2499, 2749, 3024, 3327, 3660, 4026, 4428, 4871, 5358,
    5894, 6484, 7132, 7845, 8630, 9493, 10442, 11487, 12635, 13899,
    15289, 16818, 18500, 20350, 22385, 24623, 27086, 29794, 32767
};

/*****
*      ADPCMEncoder - ADPCM encoder routine           *
*****
*      Input variables:                            *
*          short sample - 16-bit signed speech sample   *
*          struct ADPCMstate *state - ADPCM structure     *
*      Return variables:                           *
*          char - 8-bit number containing the 4-bit ADPCM code   *
*****/
```

```
char ADPCMEncoder( short sample , struct ADPCMstate *state )
{
    int code; /* ADPCM output value */
    int diff; /* Difference between sample and the predicted
               sample */

    int step; /* Quantizer step size */
    int predsample; /* Output of ADPCM predictor */
    int diffq; /* Dequantized predicted difference */
    int index; /* Index into step size table */

    /* Restore previous values of predicted sample and quantizer step
       size index
    */
    predsample = (int)(state->prevsample);
    index = state->previndex;
    step = StepSizeTable[index];

    /* Compute the difference between the acutal sample (sample) and the
       the predicted sample (predsample)
    */
    diff = sample - predsample;
    if(diff >= 0)
        code = 0;
```

```

else
{
    code = 8;
    diff = -diff;
}

/* Quantize the difference into the 4-bit ADPCM code using the
   the quantizer step size
*/
/* Inverse quantize the ADPCM code into a predicted difference
   using the quantizer step size
*/
diffq = step >> 3;
if( diff >= step )
{
    code |= 4;
    diff -= step;
    diffq += step;
}
step >>= 1;
if( diff >= step )
{
    code |= 2;
    diff -= step;
    diffq += step;
}
step >>= 1;
if( diff >= step )
{
    code |= 1;
    diffq += step;
}

/* Fixed predictor computes new predicted sample by adding the
   old predicted sample to predicted difference
*/
if( code & 8 )
    predsample -= diffq;
else
    predsample += diffq;

/* Check for overflow of the new predicted sample
*/
if( predsample > 32767 )
    predsample = 32767;
else if( predsample < -32767 )
    predsample = -32767;

/* Find new quantizer stepsize index by adding the old index
   to a table lookup using the ADPCM code
*/
index += IndexTable[code];

/* Check for overflow of the new quantizer step size index
*/
if( index < 0 )
    index = 0;
if( index > 88 )
    index = 88;

/* Save the predicted sample and quantizer step size index for
   next iteration
*/
state->prevsample = (short)predsample;
state->previndex = index;

```

```
/* Return the new ADPCM code
 */
return ( code & 0x0f );
}

/***********************
*      ADPCMDecoder - ADPCM decoder routine
***********************/
*      Input variables:
*          char code - 8-bit number containing the 4-bit ADPCM code
*          struct ADPCMstate *state - ADPCM structure
*      Return variables:
*          int - 16-bit signed speech sample
***********************/

int ADPCMDecoder(char code, struct ADPCMstate *state)
{
    int step; /* Quantizer step size */
    int predsample; /* Output of ADPCM predictor */
    int diffq; /* Dequantized predicted difference */
    int index; /* Index into step size table */

    /* Restore previous values of predicted sample and quantizer step
     * size index
    */
    predsample = (int)(state->prevsample);
    index = state->previndex;

    /* Find quantizer step size from lookup table using index
    */
    step = StepSizeTable[index];

    /* Inverse quantize the ADPCM code into a difference using the
     * quantizer step size
    */
    diffq = step >> 3;
    if( code & 4 )
        diffq += step;
    if( code & 2 )
        diffq += step >> 1;
    if( code & 1 )
        diffq += step >> 2;

    /* Add the difference to the predicted sample
    */
    if( code & 8 )
        predsample -= diffq;
    else
        predsample += diffq;

    /* Check for overflow of the new predicted sample
    */
    if( predsample > 32767 )
        predsample = 32767;
    else if( predsample < -32767 )
        predsample = -32767;

    /* Find new quantizer step size by adding the old index and a
     * table lookup using the ADPCM code
    */
    index += IndexTable[code];

    /* Check for overflow of the new quantizer step size index
    */
    if( index < 0 )
        index = 0;
    if( index > 88 )
        index = 88;
```

```
index = 88;

/* Save predicted sample and quantizer step size index for next
   iteration
*/
state->prevsample = (short)predsample;
state->previndex = index;

/* Return the new speech sample */
return( predsample );

}
```

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